Please note: Some of the questions in this former practice exam may no longer perfectly align with the AP exam. Even though these questions do not fully represent the 2020 exam, teachers indicate that imperfectly aligned questions still provide instructional value. Teachers can consult the Question Bank to determine the degree to which these questions align to the 2020 Exam.

This exam may not be posted on school or personal websites, nor electronically redistributed for any reason. This exam is provided by the College Board for AP Exam preparation. Teachers are permitted to download the materials and make copies to use with their students in a classroom setting only. To maintain the security of this exam, teachers should collect all materials after their administration and keep them in a secure location.

Further distribution of these materials outside of the secure College Board site disadvantages teachers who rely on uncirculated questions for classroom testing. Any additional distribution is in violation of the College Board's copyright policies and may result in the termination of Practice Exam access for your school as well as the removal of access to other online services such as the AP Teacher Community and Online Score Reports.

## AP Physics C: Mechanics

## **Practice Exam**

This exam may not be posted on school or personal websites, nor electronically redistributed for any reason. This Released Exam is provided by the College Board for AP Exam preparation. Teachers are permitted to download the materials and make copies to use with their students in a classroom setting only. To maintain the security of this exam, teachers should collect all materials after their administration and keep them in a secure location.

Further distribution of these materials outside of the secure College Board site disadvantages teachers who rely on uncirculated questions for classroom testing. Any additional distribution is in violation of the College Board's copyright policies and may result in the termination of Practice Exam access for your school as well as the removal of access to other online services such as the AP Teacher Community and Online Score Reports.

#### **Contents**

**Exam Instructions** 

Student Answer Sheet for the Multiple-Choice Section

Section I: Multiple-Choice Questions

Section II: Free-Response Questions

Multiple-Choice Answer Key

Course Framework Alignment and Rationales

Free-Response Scoring Guidelines

Scoring Worksheet

Question Descriptors and Performance Data

Note: This publication shows the page numbers that appeared in the **2018–19 AP Exam Instructions** book and in the actual exam. This publication was not repaginated to begin with page 1.

# AP Physics C: Mechanics Exam

Regularly Scheduled Exam Date: Monday afternoon, May 13, 2019

Late-Testing Exam Date: Wednesday morning, May 22, 2019

Section I	Total Time: 45 minutes
	Calculator Allowed
	Number of Questions: 35 (The number of questions may vary slightly depending on the form of the exam.)
	Percent of Total Score: 50%
	Writing Instrument: Pencil required
Section II	Total Time: 45 minutes
	Calculator Allowed
	Number of Questions: 3
	Percent of Total Score: 50%
	Writing Instrument: Pen with black or dark blue ink, or pencil

**Before Distributing Exams:** Check that the title on all exam covers is *Physics C: Mechanics*. If there are any exam booklets with a different title, contact the AP coordinator immediately.

#### **What Proctors Need to Bring to This Exam**

- Exam packets
- Answer sheets
- □ AP Student Packs
- □ 2018-19 AP Coordinator's Manual
- □ This book—2018-19 AP Exam Instructions
- □ AP Exam Seating Chart template
- □ School Code and Homeschool/Self-Study Codes
- □ Extra calculators
- □ Extra rulers or straightedges
- □ Pencil sharpener

- □ Container for students' electronic devices (if needed)
- □ Extra No. 2 pencils with erasers
- □ Extra pens with black or dark blue ink
- □ Extra paper
- □ Stapler
- Watch
- □ Signs for the door to the testing room
  - "Exam in Progress"
  - "Phones of any kind are prohibited during the test administration, including breaks"

Students are permitted to use rulers, straightedges, and four-function, scientific, or graphing calculators for this entire exam (Sections I and II). Before starting the exam administration, make sure each student has an appropriate calculator, and any student with a graphing calculator has a model from the approved list on page 53 of the 2018-19 AP Coordinator's Manual. See pages 50–53 of the AP Coordinator's Manual for more information. If a student does not have an appropriate calculator or has a graphing calculator not on the approved list, you may provide one from your supply. If the student does not want to use the calculator you provide or does not want to use a calculator at all, they must hand copy, date, and sign the release statement on page 52 of the AP Coordinator's Manual.

During the administration of Section II, students may have no more than two calculators on their desks. Calculators may not be shared. Calculator memories do not need to be cleared before or after the exam. Students with Hewlett-Packard 48–50 Series and Casio FX-9860 graphing calculators may use cards designed for use with these calculators. Proctors should make sure infrared ports (Hewlett-Packard) are not facing each other. Since graphing calculators can be used to store data, including text, proctors should monitor that students are using their calculators appropriately. Attempts by students to use the calculator to remove exam questions and/or answers from the room may result in the cancellation of AP Exam scores.

Tables containing equations commonly used in physics are included in each AP Exam booklet, for use during the entire exam. Students are NOT allowed to bring their own copies of the equation tables to the exam room.

Students may take both Physics C exams, Mechanics only, or Electricity and Magnetism only. The Mechanics exam is administered first, after which students taking both exams are given a break. Then the Electricity and Magnetism exam is administered. Prior to testing day, determine which exams students are taking. Those taking both Physics C exams and those taking Physics C: Mechanics only should report for the 12 noon start time (11 a.m. in Alaska). Those taking Electricity and Magnetism only should report to the testing room after the break (approximately 2 p.m., 1 p.m. in Alaska). If all students are taking Electricity and Magnetism only, you must not begin the exam before 2 p.m.

The two exams are in separate exam packets, and require separate answer sheets. At the beginning of the session, you will distribute **only** the packets and answer sheets for Mechanics. The materials for Electricity and Magnetism will be distributed after the break.

### **SECTION I: Multiple Choice**

> Do not begin the exam instructions below until you have completed the appropriate General Instructions for your group.

This exam includes survey questions. The time allowed for the survey questions is in addition to the actual test-taking time.

Make sure that you begin the exam at the designated time. Remember, you must complete a seating chart for this exam. See pages 295–296 for a seating chart template and instructions. See the 2018-19 AP Coordinator's Manual for exam seating requirements (pages 56–59).

If you are giving the regularly scheduled exam, say:

It is Monday afternoon, May 13, and you will be taking the AP Physics C: Mechanics Exam.

If you are giving the alternate exam for late testing, say:

It is Wednesday morning, May 22, and you will be taking the AP Physics C: Mechanics Exam.

Look at your exam packet and confirm that the exam title is "AP Physics C: Mechanics." Raise your hand if your exam packet contains any title other than "AP Physics C: Mechanics," and I will help you.

#### Once you confirm that all students have the correct exams, say:

In a moment, you will open the exam packet. By opening this packet, you agree to all of the AP Program's policies and procedures outlined in the 2018-19 Bulletin for AP Students and Parents.

You may now remove the shrinkwrap from the outside only of your exam packet. Do not open the Section I booklet; do not remove the shrinkwrap from the Section II materials. Put the white seals and the shrinkwrapped Section II booklet aside....

Carefully remove the AP Exam label found near the top left of your exam booklet cover. Place it on page 1 of your answer sheet on the light blue box near the top right corner that reads "AP Exam Label."...

If students accidentally place the exam label in the space for the number label or vice versa, advise them to leave the labels in place. They should not try to remove the label; their exam can still be processed correctly.

Listen carefully to all my instructions. I will give you time to complete each step. Please look up after completing each step. Raise your hand if you have any questions.

Give students enough time to complete each step. Don't move on until all students are ready.

Read the statements on the front cover of the Section I booklet....

Sign your name and write today's date....

Now print your full legal name where indicated....

Turn to the back cover of your exam booklet and read it completely. . . .

Give students a few minutes to read the entire cover.

Are there any questions? . . .

You will now take the multiple-choice portion of the exam. You should have in front of you the multiple-choice booklet and your answer sheet. You may never discuss the multiple-choice exam content at any time in any form with anyone, including your teacher and other students. If you disclose the multiple-choice exam content through any means, your AP Exam score will be canceled.

Open your answer sheet to page 2. You must complete the answer sheet using a No. 2 pencil only. Mark all of your responses beginning on page 2 of your answer sheet, one response per question. Completely fill in the circles. If you need to erase, do so carefully and completely. No credit will be given for anything written in the exam booklet. Scratch paper is not allowed, but you may use the margins or any blank space in the exam booklet for scratch work. Rulers, straightedges, and calculators may be used for the entire exam. You may place these items on your desk. Are there any questions? . . .

You have 45 minutes for this section. Open your Section I booklet and begin.



Note Start Time \_\_\_\_\_\_. Note Stop Time \_\_\_\_\_.

Check that students are marking their answers in pencil on their answer sheets and that they have not opened their shrinkwrapped Section II booklets. You should also make sure that Hewlett-Packard calculators' infrared ports are not facing each other and that students are not sharing calculators.

#### After 35 minutes, say:

There are 10 minutes remaining.

#### After 10 minutes, say:

Stop working and turn to the last page in your booklet....

You have 2 minutes to answer Questions 101–106. These are survey questions and will not affect your score. You may not go back to work on any of the exam questions. You may now begin.

To help you and your proctors make sure students are not working on the exam questions, the two pages with the survey questions are identified with a large S on the upper corner of each page. Give students 2 minutes to answer the survey questions.

#### Then say:

Close your booklet and put your answer sheet on your desk, faceup. Make sure you have your AP number label and an AP Exam label on page 1 of your answer sheet. Sit quietly while I collect your answer sheets.

Collect an answer sheet from each student. Check that each answer sheet has an AP number label and an AP Exam label.

#### After all answer sheets have been collected, say:

Now you must seal your exam booklet using the white seals you set aside earlier. Remove the white seals from the backing and press one on each area of your exam booklet cover marked "PLACE SEAL HERE." Fold each seal over the back cover. When you have finished, place the booklet on your desk, faceup. I will now collect your Section I booklet....

Collect a Section I booklet from each student. Check that each student has signed the front cover of the sealed Section I booklet.

### **SECTION II: Free Response**

#### When all Section I materials have been collected and accounted for, say:

May I have everyone's attention? Place your Student Pack on your desk. . . .

You may now remove the shrinkwrap from the Section II packet, but do not open the exam booklet until you are told to do so....

Read the bulleted statements on the front cover of the exam booklet. Look up when you have finished....

Now take an AP number label from your Student Pack and place it on the shaded box. If you don't have any AP number labels, write your AP number in the box. Look up when you have finished....

Read the last statement....

Using your pen, print the first, middle, and last initials of your legal name in the boxes and print today's date where indicated. This constitutes your signature and your agreement to the statements on the front cover. . . .

Now turn to the back cover. Using your pen, complete Items 1 through 3 under "Important Identification Information."...

Read Item 4....

I need to collect the Student Pack from anyone who will be taking another AP Exam. Keep it, however, if you will be taking the Physics C: Electricity and Magnetism exam this afternoon. If you have no other AP Exams to take, place your Student Pack under your chair now....

Read the information on the back cover of the exam booklet. Do not open the booklet until you are told to do so. Look up when you have finished....

Collect the Student Packs from students who are taking any other AP Exams this year.

#### Then say:

Are there any questions?...

Rulers, straightedges, and calculators may be used for Section II. Be sure these items are on your desk....

You have 45 minutes to complete Section II. You are responsible for pacing yourself and may proceed freely from one question to the next. You must write your answers in the exam booklet using a pen with black or dark blue ink or a No. 2 pencil. If you use a pencil, be sure that your writing is dark enough to be easily read. If you need more paper to complete your responses, raise your hand. At the top of each extra sheet of paper you use, write only:

- vour AP number.
- the exam title, and
- the question number you are working on.

Do not write your name. Are there any questions? . . .

You may begin.



Note Start Time \_\_\_\_\_\_. Note Stop Time \_\_\_\_\_.

You should also make sure that Hewlett-Packard calculators' infrared ports are not facing each other and that students are not sharing calculators.

#### After 35 minutes, say:

There are 10 minutes remaining.

#### After 10 minutes, say:

Stop working and close your exam booklet. Place it on your desk, faceup. . . .

If any students used extra paper for a question in the free-response section, have those students staple the extra sheet(s) to the first page corresponding to that question in their free-response exam booklets. Complete an Incident Report after the exam and return these free-response booklets with the extra sheets attached in the Incident Report return envelope (see page 68 of the 2018-19 AP Coordinator's Manual for complete details).

#### Then say:

Remain in your seat, without talking, while the exam materials are collected....

Collect a Section II booklet from each student. Check for the following:

- Exam booklet front cover: The student placed an AP number label on the shaded box and printed their initials and today's date.
- Exam booklet back cover: The student completed the "Important Identification Information" area.

When all exam materials have been collected and accounted for, return to students who are taking Mechanics only any electronic devices you may have collected before the start of the exam.

#### If you are giving the regularly scheduled exam, say:

You may not discuss or share the free-response exam content with anyone unless it is released on the College Board website in about two days. Your AP Exam score results will be available online in July.

#### If you are giving the alternate exam for late testing, say:

None of the content in this exam may ever be discussed or shared in any way at any time. Your AP Exam score results will be available online in July.

If any students completed the AP number card at the beginning of this exam and are about to be dismissed say:

Please remember to take your AP number card with you. You will need the information on this card to view your scores and order AP score reporting services online.

If no students are taking Physics C: Electricity and Magnetism, say:

You are now dismissed.

If some students are taking Physics C: Electricity and Magnetism, say:

Those of you taking Mechanics only are now dismissed.

The students taking the Electricity and Magnetism exam now get a 10-minute break. Remember that the Electricity and Magnetism exam cannot begin before 2 p.m., but should start before 3 p.m.

#### After the students taking Mechanics only have left, say:

If you will also be taking the Physics C: Electricity and Magnetism exam, please listen carefully to these instructions before we take a 10-minute break. Please put all of your calculators under your chair. Your calculators and all items you placed under your chair at the beginning of this exam, including your Student Pack, must stay there, and you are not permitted to open or access them in any way. You are not allowed to consult teachers, other students, notes, textbooks, or any other resources during the break. You may not make phone calls, send text messages, check email, use a social networking site, or access any electronic or communication device. You may not leave the designated break area. If you do not follow these rules, your score will be canceled. Are there any questions? . . .



You may begin your break. Testing will resume at \_\_\_\_\_

If you will be administering Physics C: Electricity and Magnetism at 2 p.m., be sure all exam materials are kept secure during the break. When the students return from break, turn to page 237 and begin the exam administration for Physics C: Electricity and Magnetism.

If you have no students taking Physics C: Electricity and Magnetism, return all exam materials to secure storage until they are shipped back to the AP Program. (See page 27 of the 2018-19 AP Coordinator's Manual for more information about secure storage.)

#### **After-Exam Tasks**

Be sure to give the completed seating chart to the AP coordinator. Schools must retain seating charts for at least six months (unless the state or district requires that they be retained for a longer period of time). Schools should not return any seating charts in their exam shipments unless they are required as part of an Incident Report.

**NOTE:** If you administered exams to students with accommodations, review the 2018-19 AP Coordinator's Manual and the 2018-19 AP SSD Guidelines for information about completing the Nonstandard Administration Report (NAR) form, and returning these exams.

The exam proctor should complete the following tasks if asked to do so by the AP coordinator. Otherwise, the AP coordinator must complete these tasks:

- Complete an Incident Report for any students who used extra paper for the free-response section. (Incident Report forms are provided in the coordinator packets sent with the exam shipments.) These forms must be completed with a No. 2 pencil. It is best to complete a single Incident Report for multiple students per exam subject, per administration (regular or late testing), as long as all required information is provided. Include all exam booklets with extra sheets of paper in an Incident Report return envelope (see page 68 of the 2018-19 AP Coordinator's Manual for complete details).
- Before storing materials, check the "School Use Only" section on page 1 of the answer sheet and:
  - Fill in the appropriate section number circle in order to access a separate
     AP Instructional Planning Report (for regularly scheduled exams only) or subject
     score roster at the class section or teacher level. See "Post-Exam Activities" in the
     2018-19 AP Coordinator's Manual.
  - Check your list of students who are eligible for fee reductions and fill in the appropriate circle on their registration answer sheets.

Name:\_\_\_\_\_

## Answer Sheet for AP Physics C: Mechanics Practice Exam, Section I

No.	Answer
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	
11	
12	
13	
14	
15	
16	
17	
18	

No.	Answer
19	_
20	_
21	
22	_
23	
24	
25	
26	
27	
28	
29	
30	
31	
32	
33	
34	
35	

## AP<sup>®</sup> Physics C: Mechanics Exam

#### **SECTION I: Multiple Choice**

2019

#### DO NOT OPEN THIS BOOKLET UNTIL YOU ARE TOLD TO DO SO.

#### At a Glance

**Total Time** 45 minutes

**Number of Questions** 

**Percent of Total Score** 50%

**Writing Instrument** Pencil required

**Electronic Device** 

Calculator allowed

#### Instructions

Section I of this exam contains 35 multiple-choice questions. For these questions, fill in only the circles for numbers 1 through 35 on your answer sheet. A table of information and lists of equations that may be helpful are in the booklet. Calculators, rulers and straightedges may be used in this section.

Indicate all of your answers to the multiple-choice questions on the answer sheet. No credit will be given for anything written in this exam booklet, but you may use the booklet for notes or scratch work. After you have decided which of the suggested answers is best, completely fill in the corresponding circle on the answer sheet. Give only one answer to each question. If you change an answer, be sure that the previous mark is erased completely. Here is a sample question and answer.

#### Sample Question Sample Answer

Chicago is a







(A) state

(B) city

(C) country

(D) continent

(E) village

Use your time effectively, working as quickly as you can without losing accuracy. Do not spend too much time on any one question. Go on to other questions and come back to the ones you have not answered if you have time. It is not expected that everyone will know the answers to all of the multiple-choice questions.

Your total score on the multiple-choice section is based only on the number of questions answered correctly. Points are not deducted for incorrect answers or unanswered questions.

> Form I Form Code 4PBP4-S

#### ADVANCED PLACEMENT PHYSICS C TABLE OF INFORMATION

#### CONSTANTS AND CONVERSION FACTORS

Proton mass,  $m_p = 1.67 \times 10^{-27} \text{ kg}$ 

Neutron mass,  $m_n = 1.67 \times 10^{-27} \text{ kg}$ 

Electron mass,  $m_e = 9.11 \times 10^{-31} \text{ kg}$ 

Avogadro's number,  $N_0 = 6.02 \times 10^{23} \text{ mol}^{-1}$ 

Universal gas constant,  $R = 8.31 \text{ J/(mol \cdot K)}$ 

Boltzmann's constant,  $k_B = 1.38 \times 10^{-23} \text{ J/K}$ 

Electron charge magnitude,  $e = 1.60 \times 10^{-19} \text{ C}$ 

1 electron volt,  $1 \text{ eV} = 1.60 \times 10^{-19} \text{ J}$ 

Speed of light,  $c = 3.00 \times 10^8$  m/s

Universal gravitational

constant,

 $G = 6.67 \times 10^{-11} \left( \text{N} \cdot \text{m}^2 \right) / \text{kg}^2$ 

Acceleration due to gravity at Earth's surface,

o gravity  $g = 9.8 \text{ m/s}^2$ 

1 unified atomic mass unit,

Planck's constant,

 $1 \text{ u} = 1.66 \times 10^{-27} \text{ kg} = 931 \text{ MeV}/c^2$ 

 $h = 6.63 \times 10^{-34} \text{ J} \cdot \text{s} = 4.14 \times 10^{-15} \text{ eV} \cdot \text{s}$ 

 $hc = 1.99 \times 10^{-25} \text{ J} \cdot \text{m} = 1.24 \times 10^3 \text{ eV} \cdot \text{nm}$ 

Vacuum permittivity,

 $\varepsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 / (\text{N} \cdot \text{m}^2)$ 

Coulomb's law constant,  $k = 1/(4\pi\epsilon_0) = 9.0 \times 10^9 \text{ (N·m}^2)/\text{C}^2$ 

Vacuum permeability,

$$\mu_0 = 4\pi \times 10^{-7} \text{ (T-m)/A}$$

Magnetic constant,  $k' = \mu_0/(4\pi) = 1 \times 10^{-7} \text{ (T-m)/A}$ 

1 atmosphere pressure,

 $1 \text{ atm} = 1.0 \times 10^5 \text{ N/m}^2 = 1.0 \times 10^5 \text{ Pa}$ 

	meter,	m	mole,	mol	watt,	W	farad,	F
LINIT	kilogram,	kg	hertz,	Hz	coulomb,	С	tesla,	T
UNIT SYMBOLS	second,	S	newton,	N	volt,	V	degree Celsius,	°C
SIMBOLS	ampere,	A	pascal,	Pa	ohm,	Ω	electron volt,	eV
	kelvin,	K	joule,	J	henry,	Н		

	PREFIXES				
Factor	Prefix	Symbol			
10 <sup>9</sup>	giga	G			
10 <sup>6</sup>	mega	M			
10 <sup>3</sup>	kilo	k			
$10^{-2}$	centi	С			
$10^{-3}$	milli	m			
$10^{-6}$	micro	μ			
$10^{-9}$	nano	n			
$10^{-12}$	pico	p			

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
$\theta$	0°	30°	37°	45°	53°	60°	90°
$\sin \theta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	8

The following assumptions are used in this exam.

- I. The frame of reference of any problem is inertial unless otherwise stated
- II. The direction of current is the direction in which positive charges would drift.
- III. The electric potential is zero at an infinite distance from an isolated point charge.
- IV. All batteries and meters are ideal unless otherwise stated.
- V. Edge effects for the electric field of a parallel plate capacitor are negligible unless otherwise stated.

#### ADVANCED PLACEMENT PHYSICS C EQUATIONS

#### **MECHANICS**

$v_x = v_{x0} + a_x t$	a = acceleration
1 2	E = energy
$x = x_0 + v_{x0}t + \frac{1}{2}a_xt^2$	F = force
2 2 2 2 (2 2 2 )	f = frequency
$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$	h = height
$\sum \vec{r} = \vec{r}$	I = rotational inertia
$\sum F = F_{max}$	

$$\vec{a} = \frac{\sum F}{m} = \frac{F_{net}}{m}$$
 $J = \text{impulse}$ 
 $K = \text{kinetic energy}$ 
 $K = \text{spring constant}$ 

$$\vec{F} = \frac{d\vec{p}}{dt}$$
  $k = \text{spring constant}$   $\ell = \text{length}$ 

$$\vec{J} = \int \vec{F} \, dt = \Delta \vec{p} \qquad \qquad L = \text{angular momentum}$$
 
$$\vec{J} = \int \vec{F} \, dt = \Delta \vec{p} \qquad \qquad m = \text{mass}$$

$$\vec{p} = m\vec{v}$$
  $P = \text{power}$   $p = \text{momentum}$   $r = \text{radius or distance}$ 

$$\left| \vec{F}_f \right| \le \mu \left| \vec{F}_N \right| \qquad \qquad T = \text{ period}$$
 
$$t = \text{ time}$$

$$\Delta E = W = \int \vec{F} \cdot d\vec{r}$$

$$U = \text{potential energy}$$

$$v = \text{velocity or speed}$$

$$K = \frac{1}{2}mv^2$$
  $W = \text{work done on a system}$   
 $x = \text{position}$ 

$$P = \frac{dE}{dt}$$

$$\mu = \text{coefficient of friction}$$

$$\theta = \text{angle}$$

$$\tau = \text{torque}$$

$$P = \vec{F} \cdot \vec{v}$$
  $\omega = \text{angular speed}$   $\alpha = \text{angular acceleration}$ 

$$\Delta U_g = mg\Delta h$$
  $\phi = \text{phase angle}$   $\vec{F}_s = -k\Delta \vec{x}$ 

$$a_{c} = \frac{v^{2}}{r} = \omega^{2} r$$

$$U_{s} = \frac{1}{2} k (\Delta x)^{2}$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$$

$$x = x_{\text{max}} \cos(\omega t + \phi)$$

$$T = 2\pi - 1$$

$$U = \frac{2\pi}{I} = \frac{1}{I}$$

$$I = \int r^2 dm = \sum mr^2$$

$$T_{s} = 2\pi \sqrt{\frac{m}{k}}$$

$$T_{s} = 2\pi \sqrt{\frac{m}{k}}$$

$$T_{p} = 2\pi \sqrt{\frac{\ell}{g}}$$

$$v = r\omega$$
  $|\vec{F}_G| = \frac{Gm_1m_2}{r^2}$ 

$$K = \frac{1}{2}I\omega^2 \qquad U_G = -\frac{Gm_1m_2}{r}$$

$$\omega = \omega_0 + \alpha t$$

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

#### ELECTRICITY AND MAGNETISM

$ \vec{r}  = 1  q_1q_2 $	A = area
$\left  \vec{F}_E \right  = \frac{1}{4\pi\varepsilon_0} \left  \frac{q_1 q_2}{r^2} \right $	B = magnetic field
	C = capacitance
$\vec{E} = \frac{\vec{F}_E}{\vec{F}_E}$	d = distance
$E = \frac{q}{q}$	E = electric field
-	$\varepsilon = \text{emf}$
$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\varepsilon_0}$	F = force
$\epsilon_0$	I = current

$$E_x = -\frac{dV}{dx}$$
 
$$J = \text{current density}$$
 
$$L = \text{inductance}$$
 
$$\ell = \text{length}$$

$$\Delta V = -\int \vec{E} \cdot d\vec{r}$$
  $n = \text{number of loops of wire}$  per unit length  $N = \text{number of charge carriers}$ 

$$V = \frac{1}{4\pi\varepsilon_0} \sum_{i} \frac{q_i}{r_i}$$
 per unit volume 
$$P = \text{power}$$
 
$$Q = \text{charge}$$
 
$$Q = \text{charge}$$
 
$$Q = \text{point charge}$$

$$U_E = qV = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r}$$
  $q = \text{point charge}$   
 $R = \text{resistance}$   
 $r = \text{radius or distance}$ 

$$\Delta V = \frac{Q}{C}$$

$$t = \text{time}$$

$$U = \text{potential or stored energy}$$

$$C = \frac{\kappa \varepsilon_0 A}{d}$$
  $V = \text{electric potential}$   $v = \text{velocity or speed}$   $\rho = \text{resistivity}$   $\rho = \text{flux}$ 

$$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$$
  $\kappa = \text{dielectric constant}$  
$$\vec{F}_M = q\vec{v} \times \vec{B}$$

$$I = \frac{dQ}{dt} \qquad \qquad \oint \vec{B} \cdot d\vec{\ell} = \mu_0 I$$

$$U_C = \frac{1}{2}Q\Delta V = \frac{1}{2}C(\Delta V)^2 \qquad d\vec{B} = \frac{\mu_0}{4\pi} \frac{I \, d\vec{\ell} \times \hat{r}}{r^2}$$

$$R = \frac{\rho\ell}{4} \qquad \qquad \vec{F} = \int I \, d\vec{\ell} \times \vec{B}$$

$$R = \frac{1}{A}$$
 $\vec{E} = \rho \vec{J}$ 
 $\vec{B}_S = \mu_0 n I$ 

$$I = Nev_d A \qquad \Phi_B = \int \vec{B} \cdot d\vec{A}$$

$$I = \frac{\Delta V}{R} \qquad \qquad \boldsymbol{\varepsilon} = \oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi_B}{dt}$$

$$R_{s} = \sum_{i} R_{i} \qquad \qquad \varepsilon = -L \frac{dI}{dt}$$

$$\frac{1}{R_n} = \sum_{i} \frac{1}{R_i} \qquad U_L = \frac{1}{2} L I^2$$

$$P = I\Delta V$$

#### GEOMETRY AND TRIGONOMETRY

#### Rectangle

A = area

A = bh

C = circumference

Triangle

V = volumeS =surface area

b = base

 $A = \frac{1}{2}bh$ 

Circle

h = height

 $A = \pi r^2$ 

 $\ell = length$ 

 $C = 2\pi r$ 

w = widthr = radius

s = arc length

 $s = r\theta$ 

 $\theta$  = angle

Rectangular Solid

$$V = \ell w h$$

Cylinder

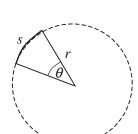
$$V = \pi r^2 \ell$$

$$S = 2\pi r\ell + 2\pi r^2$$

Sphere

$$V = \frac{4}{3}\pi r^3$$

$$S = 4\pi r^2$$



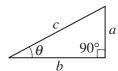
#### Right Triangle

$$a^2 + b^2 = c^2$$

$$\sin\theta = \frac{a}{c}$$

$$\cos\theta = \frac{b}{c}$$

$$\tan \theta = \frac{a}{b}$$



#### **CALCULUS**

$$\frac{df}{dx} = \frac{df}{du}\frac{du}{dx}$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(e^{ax}) = ae^{ax}$$

$$\frac{d}{dx}(\ln ax) = \frac{1}{x}$$

$$\frac{d}{dx}[\sin(ax)] = a\cos(ax)$$

$$\frac{d}{dx}[\cos(ax)] = -a\sin(ax)$$

$$\int x^n \, dx = \frac{1}{n+1} x^{n+1}, \, n \neq -1$$

$$\int e^{ax} dx = \frac{1}{a} e^{ax}$$

$$\int \frac{dx}{x+a} = \ln|x+a|$$

$$\int \cos(ax) dx = \frac{1}{a} \sin(ax)$$

$$\int \sin(ax) dx = -\frac{1}{a} \cos(ax)$$

#### **VECTOR PRODUCTS**

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$|\vec{A} \times \vec{B}| = AB\sin\theta$$

#### PHYSICS C: MECHANICS

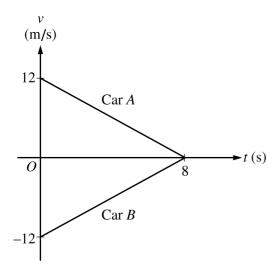
#### **SECTION I**

#### Time—45 minutes

**35 Questions** 

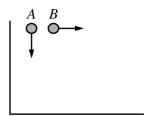
**Directions:** Each of the questions or incomplete statements below is followed by five suggested answers or completions. Select the one that is best in each case and then fill in the corresponding circle on the answer sheet.

**Note:** To simplify calculations, you may use  $g = 10 \,\text{m/s}^2$  in all problems.



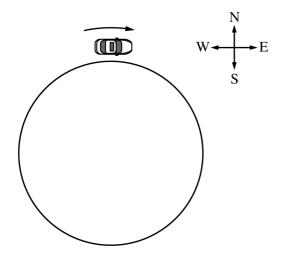
- Cars A and B are moving in opposite directions along a straight road. They pass each other at time t = 0. Their velocities v are given as a function of time t in the graph above. The distance between the cars at t = 8 s is
  - (A) Zero
  - (B) 24 m
  - (C) 48 m
  - (D) 96 m
  - (E) 192 m

- 2. A particle is moving along the y-axis. The particle's position as a function of time is given by  $y = \alpha t^3 \beta t + \phi$ , where  $\alpha = 1 \text{ m/s}^3$ ,  $\beta = 4 \text{ m/s}$ , and  $\phi = 3 \text{ m}$ . What is the particle's acceleration at time t = 3.0 s?
  - (A)  $6.0 \text{ m/s}^2$
  - (B)  $9.0 \text{ m/s}^2$
  - (C)  $18 \text{ m/s}^2$
  - (D)  $23 \text{ m/s}^2$
  - (E)  $27 \text{ m/s}^2$



- 3. Two stones, represented in the figure above, are thrown from the same height with the same initial speed. Stone *A* is thrown vertically downward and stone *B* is thrown horizontally. If the stones are thrown at the same time and air resistance is negligible, which of the following is true?
  - (A) The two stones will reach the ground at the same time with the same speed.
  - (B) The two stones will reach the ground at the same time but with different speeds.
  - (C) Stone *A* will reach the ground first, but stone *B* will have the greater speed just before hitting the ground.
  - (D) Stone A will reach the ground first, but the two stones will have the same speed just before they hit the ground.
  - (E) Stone *A* will reach the ground first, and will have the greater speed just before hitting the ground.

**Questions 4-6** 

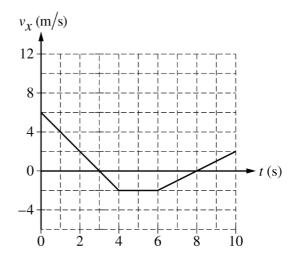


Note: Figure not drawn to scale.

A car is traveling clockwise around a circular racetrack of radius 1440 m. When the car is at the northernmost point on the circle, as shown above, it has a speed of 36.0 m/s and is slowing down at a rate of  $1.20 \text{ m/s}^2$ .

- 4. The direction of the velocity of the car is
  - (A) due east
  - (B) south of east
  - (C) due south
  - (D) south of west
  - (E) due west
- 5. The direction of the acceleration of the car is
  - (A) due east
  - (B) south of east
  - (C) due south
  - (D) south of west
  - (E) due west
- 6. What is the magnitude of the acceleration of the car?
  - (A)  $0.30 \text{ m/s}^2$
  - (B)  $0.90 \text{ m/s}^2$
  - (C)  $1.2 \text{ m/s}^2$
  - (D)  $1.5 \text{ m/s}^2$
  - (E)  $2.1 \text{ m/s}^2$

**Questions 7-8** 



A car moves in a straight line along the *x*-axis. The velocity of the car  $v_x$  as a function of time *t* is shown in the graph above. The position *x* of the car at t = 0 is x = 0.

- 7. The average acceleration  $a_x$  of the car during the interval of 0 to 10 s is most nearly
  - (A)  $-2.0 \text{ m/s}^2$
  - (B)  $-0.40 \text{ m/s}^2$
  - (C)  $+0.40 \text{ m/s}^2$
  - (D)  $+1.0 \text{ m/s}^2$
  - (E)  $+2.0 \text{ m/s}^2$
- 8. The average velocity of the car during the interval of 0 to 10 s is most nearly
  - (A) -1.4 m/s
  - (B) +0.40 m/s
  - (C) +1.4 m/s
  - (D) +1.8 m/s
  - (E) +4.0 m/s



- 9. Two blocks rest on a table, as shown above. The bottom block is pulled to the right by an applied force  $\vec{F}$  that is strong enough so that the two blocks do not move together (i.e., they do not have the same acceleration or velocity). There is friction between the blocks, but the tabletop is frictionless. When the top block leaves the bottom block, where does it land and why?
  - (A) The top block will land directly below where it starts because objects at rest tend to stay at rest.
  - (B) The top block will land to the left of where it starts because of the static friction between the blocks.
  - (C) The top block will land to the left of where it starts because of the kinetic friction between the blocks.
  - (D) The top block will land to the right of where it starts because of the static friction between the blocks.
  - (E) The top block will land to the right of where it starts because of the kinetic friction between the blocks.

10. A sphere of mass m is dropped from the top of a building and reaches the ground before achieving terminal velocity. The force of air resistance that acts on the sphere as it falls is given by F = -kv, where k is a positive constant and v is the velocity of the sphere. What happens to the magnitude of the sphere's velocity and acceleration, and to the distance it falls during each second, as the sphere approaches the ground?

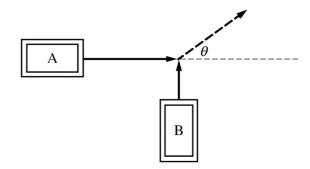
$\underline{\mathbf{N}}$	<u>Sagnitude of Velocity</u>	Magnitude of Acceleration	Distance of Fall Each Second
(A)	Increases	Increases	Increases
(B)	Increases	Decreases	Increases
(C)	Increases	Decreases	Decreases
(D)	Decreases	Increases	Decreases
(E)	Decreases	Decreases	Increases

#### **Questions 11-12**

An object of mass 0.5 kg is given an initial velocity and then slides across a horizontal surface. The object experiences a resistive force that is a function of velocity. The velocity v of the object as a function of time t is given by  $v(t) = \alpha e^{-\beta t}$ , where  $\alpha = 2$  m/s and  $\beta = 3$  s<sup>-1</sup>.

- 11. Which of the following is a correct expression for the net force, in newtons, exerted on the object as a function of time?
  - (A)  $-6e^{-3t}$
  - (B)  $-3e^{-3t}$
  - (C)  $e^{-3t}$
  - (D)  $2e^{-3t}$
  - (E)  $\frac{2}{3(1-e^{-3t})}$
- 12. The energy dissipated due to the resistive force after a very long time is most nearly
  - (A) 0.5 J
  - (B) 1 J
  - (C) 2 J
  - (D) 4 J
  - (E) infinity

#### **Questions 13-14**

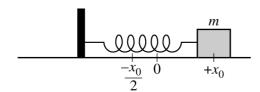


Top View

Cart A is traveling east when it collides with cart B, which is traveling north. Cart A has a mass of 3.05 kg, and cart B has a mass of 2.10 kg. The two carts travel together as a single object on a horizontal surface at an angle  $\theta$  relative to due east, as shown above.

- 13. In one trial, the initial speed of cart A is 2.5 m/s and the initial speed of cart B is 1.5 m/s. The angle  $\theta$  relative to east that the carts travel after the collision is most nearly
  - (A) 22°
  - (B) 36°
  - (C)  $45^{\circ}$
  - (D) 54°
  - (E)  $62^{\circ}$
- 14. In another trial, the speed of the carts immediately after the collision is 0.60 m/s, and the carts slide 0.24 m on the horizontal surface before coming to rest. The coefficient of kinetic friction between the sliding carts and the surface is most nearly
  - (A) 0.08
  - (B) 0.13
  - (C) 0.19
  - (D) 0.25
  - (E) 0.75

#### **Questions 15-17**



A block of mass m is on a rough horizontal surface and is attached to a spring with spring constant k. The coefficient of kinetic friction between the surface and the block is  $\mu$ . When the block is at position x = 0, the spring is at its unstretched length. The block is pulled to position  $x = +x_0$ , as shown above, and released from rest. The block then travels to the left and passes through x = 0 before coming momentarily to rest at position  $x = -x_0/2$ .

- 15. Which of the following is a correct expression for the kinetic energy of the block as it first travels through position x = 0?
  - (A) 0
  - (B)  $kx_0^2/2$
  - (C)  $kx_0^2/2 \mu mgx_0$
  - (D)  $kx_0^2/2 3\mu mgx_0/2$
  - (E)  $kx_0^2/2 2\mu mgx_0$

- 16. Which of the following is a correct expression for the coefficient of kinetic friction  $\mu$ ?
  - (A)  $\frac{kx_0}{4mg}$
  - (B)  $\frac{kx_0}{2mg}$
  - (C)  $\frac{3kx_0}{4mg}$
  - (D)  $\frac{kx_0}{mg}$
  - (E)  $\frac{2kx_0}{mg}$
- 17. Which of the following is a differential equation that could be used to solve for the block's position *x* as a function of time *t* when it is moving to the left?

(A) 
$$m\frac{d^2x}{dt^2} = kx + \mu mg$$

(B) 
$$m\frac{d^2x}{dt^2} = kx - \mu mg$$

(C) 
$$m\frac{d^2x}{dt^2} = -kx + \mu mg$$

(D) 
$$m\frac{d^2x}{dt^2} = -kx - \mu mg$$

(E) 
$$m\frac{d^2x}{dt^2} = kx$$

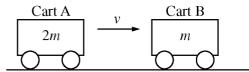
#### **Questions 18-19**



In the diagram above, a block of mass M is initially at rest on a horizontal surface at the base of an inclined plane. The surface and plane have negligible friction. The block is struck by a projectile of mass m traveling with a horizontal velocity  $v_i$ . The projectile becomes embedded in the block, and they move together to the right with speed  $v_f$ .

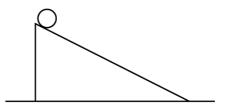
- 18. Which of the following is a correct expression for  $v_f$ ?
  - (A)  $\sqrt{gh}$
  - (B)  $\sqrt{v_i^2 + 2gh}$
  - (C)  $\frac{m}{(m+M)}v_i$
  - (D)  $\frac{m}{M}v_i$
  - (E)  $\frac{M}{m}v_i$
- 19. The block and projectile smoothly transition onto the inclined plane. Which of the following is a correct expression for the maximum height that the block moves up the inclined plane in terms of  $v_f$ ?
  - (A)  $\frac{v_f^2}{2g}$
  - (B)  $\frac{v_f}{\sqrt{2g}}$
  - (C)  $\frac{Mv_f^2}{2mg}$
  - (D)  $\frac{2g}{v_f^2}$
  - (E)  $\frac{2g}{v_f}$

- 20. The net force F acting on an object that moves along a straight line is given as a function of time t by  $F(t) = \kappa t^2 + \tau$ , where  $\kappa = 1 \text{ N/s}^2$  and  $\tau = 1 \text{ N}$ . What is the change in momentum of the object from t = 0 s to t = 3 s?
  - (A)  $6 \text{ kg} \cdot \text{m/s}$
  - (B)  $10 \text{ kg} \cdot \text{m/s}$
  - (C) 12 kg·m/s
  - (D)  $30 \text{ kg} \cdot \text{m/s}$
  - (E) It cannot be determined without knowing the initial momentum of the object.

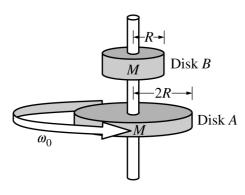


- 21. Cart A of mass 2*m* is moving with velocity *v* to the right on a horizontal frictionless track, as shown above, when it collides with cart B of mass *m*. Cart B is initially at rest, and the collision is perfectly elastic. Which of the following best describes the motion of the carts immediately after the collision?
  - (A) Cart A is moving to the left, and cart B is moving to the right.
  - (B) Cart A is moving to the left, and cart B remains stationary.
  - (C) Cart A is stationary, and cart B is moving to the right.
  - (D) Both carts move to the right, and they are stuck together.
  - (E) Both carts move to the right, but they are not stuck together.

- 22. A ball of mass *m* is dropped from rest at a height *h* and collides elastically with the floor, rebounding to its original height. What is the magnitude of the net impulse on the ball during the collision with the floor?
  - (A) Zero
  - (B)  $m\sqrt{gh}$
  - (C)  $m\sqrt{2gh}$
  - (D)  $m\sqrt{4gh}$
  - (E)  $m\sqrt{8gh}$



- 23. A sphere starts from rest at the top of a ramp, as shown above. It rolls without slipping down the ramp. The potential energy of the sphere-Earth system is zero at the bottom of the ramp. Which of the following is true of the sphere when it reaches the bottom of the ramp?
  - (A) Its rotational kinetic energy equals the initial potential energy of the sphere-Earth system.
  - (B) Its translational kinetic energy equals the initial potential energy of the sphere-Earth system.
  - (C) Its translational kinetic energy and rotational kinetic energy are equal.
  - (D) The sum of its translational kinetic energy and rotational kinetic energy equals the initial potential energy of the sphere-Earth system.
  - (E) The sum of its translational kinetic energy and rotational kinetic energy equals the energy lost because of friction.

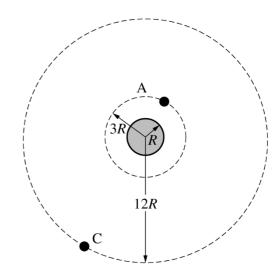


- 24. Two horizontal disks of mass M have the radii shown above. Disk A is attached to an axle of negligible mass spinning freely with angular velocity  $\omega_0$ . Disk B, not attached to the axle and initially held at rest, is released and drops down onto disk A. When both disks spin together without slipping, the angular velocity  $\omega_f$  of the disks is
  - (A)  $\frac{1}{3}\omega_0$
  - (B)  $\frac{1}{2}\omega_0$
  - (C)  $\frac{2}{3}\omega_0$
  - (D)  $\frac{4}{5}\omega_0$
  - (E)  $\frac{2}{\sqrt{5}}\omega_0$

- 25. A satellite is in a circular orbit such that it stays directly over the same point on Earth's equator. Which of the following must be true for the satellite?
  - I. It must have a specific mass.
  - II. It must have a specific altitude.
  - III. It must have a specific angular velocity.
  - (A) I only
  - (B) II only
  - (C) I and III only
  - (D) II and III only
  - (E) I, II, and III

- 26. Spheres X, Y, and Z have the masses and locations indicated in the figure above. What is the magnitude of the net gravitational force on sphere X due to the other two spheres?
  - (A)  $\frac{Gm^2}{2r^2}$
  - (B)  $\frac{Gm^2}{r^2}$
  - (C)  $\frac{11Gm^2}{9r^2}$
  - (D)  $\frac{5Gm^2}{4r^2}$
  - (E)  $\frac{2Gm^2}{r^2}$

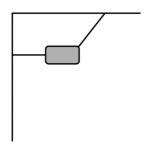
#### **Questions 27-28**



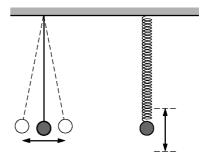
Note: Figure not drawn to scale.

Two identical satellites orbit a planet of radius *R* in circular orbits A and C of radii 3*R* and 12*R*, respectively, as shown above.

- 27. How does the magnitude of the gravitational force  $F_A$  between the planet and satellite in orbit A compare to the magnitude of the gravitational force  $F_C$  between the planet and satellite in orbit C?
  - (A)  $F_A = 2F_C$
  - (B)  $F_{\rm A} = 3F_{\rm C}$
  - (C)  $F_{A} = 4F_{C}$
  - (D)  $F_{A} = 12F_{C}$
  - (E)  $F_{\rm A} = 16F_{\rm C}$
- 28. The speed of the satellite in orbit A is  $v_A$ . The speed of the satellite in orbit C is  $v_C$ . The ratio  $v_A/v_C$  is
  - (A) 1/2
  - (B) 1/1
  - (C) 2/1
  - (D) 4/1
  - (E) 12/1



- 29. At the surface of Earth, an object is suspended by two cords. One cord is horizontal and one cord is at an angle to the horizontal, as shown in the figure above. The tension in the horizontal cord is  $T_H$ . If the assembly is moved to the surface of a planet with the same average density and twice the radius of Earth, the new tension in the horizontal cord will be
  - (A)  $T_H/2$
  - (B)  $T_H/4$
  - (C)  $T_H$
  - (D)  $2T_H$
  - (E)  $4T_H$
- 30. A space shuttle has a mass of 90,000 kg. In order to stay in a circular orbit, it must have a velocity of 8000 m/s. The pilot discovers that the shuttle has slowed down to 7900 m/s, and the shuttle's speed needs to increase. If the thrusters exert a constant force of 50,000 N, how long do the thrusters have to exert this force in order to return the shuttle to orbital velocity?
  - (A) 30 s
  - (B) 60 s
  - (C) 120 s
  - (D) 180 s
  - (E) 240 s



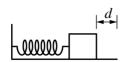
31. A pendulum and a spring both have a 1 kg sphere attached to their ends and have the same length when in equilibrium, as shown in the figure above. They both oscillate with the same period. If the 1 kg spheres are replaced with 2 kg spheres and the amplitudes of oscillation are unchanged, which of the following is true about the resultant period of oscillation for each?

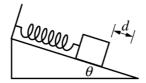
<u>Pendulum</u>	Spring
(A) Remains the same	Decreases
(B) Remains the same	Increases
(C) Remains the same	Remains the same
(D) Increases	Remains the same
(E) Increases	Increases

#### **Questions 32-34**

System A

System B

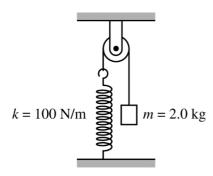




Systems A and B contain identical ideal springs and identical blocks that can slide along a surface of negligible friction. In system A, the surface is horizontal. In system B, the surface makes an angle  $\theta$  with the horizontal. Initially, both blocks are at rest and in equilibrium. Each block is then pulled the same distance d in the direction shown in the figures and released from rest at t = 0.

- 32. After the block in system A is released from rest, the time for the block to first reach a maximum speed is  $\Delta t_{\rm A}$ . After the block in system B is released, the time for the block to first reach a maximum speed is
  - (A)  $\Delta t_A$
  - (B)  $\Delta t_{\rm A} (\sin \theta)$
  - (C)  $\Delta t_{\rm A}/(\sin\theta)$
  - (D)  $\Delta t_{\rm A} (\cos \theta)$
  - (E)  $\Delta t_{\rm A}/(\cos\theta)$

- 33. For system A, when the block is halfway between its release position and its equilibrium position, the block's kinetic energy is K and the elastic potential energy of the spring-block system is U. The ratio K/U is
  - (A) 1/3
  - (B) 1/2
  - (C) 1/1
  - (D) 2/1
  - (E) 3/1
- 34. A student wants to use an apparatus similar to system B to measure the acceleration due to gravity *g*. If the mass of the block, the force constant of the spring, and the angle of the incline are known, what additional data must be measured to determine an experimental value for *g*?
  - I. The stretch of the spring at the equilibrium position
  - II. The speed of the block as it passes the equilibrium position
  - III. The time interval between two consecutive passes through the equilibrium position
  - (A) I only
  - (B) II only
  - (C) I and II
  - (D) II and III
  - (E) I and III



- 35. A 2.0 kg block is attached to a string that passes over a pulley and is attached to an ideal spring of spring constant k = 100 N/m, as shown above. The pulley and string have negligible mass, and there is negligible friction in the pulley. The block is held in place with the spring at its original unstretched length and then released from rest. The amplitude of the resulting oscillation is most nearly
  - (A) 4.0 cm
  - (B) 2.0 cm
  - (C) 10 cm
  - (D) 20 cm
  - (E) 40 cm

#### STOP

#### **END OF MECHANICS SECTION I**

## IF YOU FINISH BEFORE TIME IS CALLED, YOU MAY CHECK YOUR WORK ON MECHANICS SECTION I ONLY.

DO NOT	TURN TO	<b>ANY OTH</b>	ER TEST	MATERIALS.
--------	---------	----------------	---------	------------

\_\_\_\_\_

#### MAKE SURE YOU HAVE DONE THE FOLLOWING.

- PLACED YOUR AP NUMBER LABEL ON YOUR ANSWER SHEET
- WRITTEN AND GRIDDED YOUR AP NUMBER CORRECTLY ON YOUR ANSWER SHEET
- TAKEN THE AP EXAM LABEL FROM THE FRONT OF THIS BOOKLET AND PLACED IT ON YOUR ANSWER SHEET

## AP® Physics C: Mechanics Exam

**SECTION II: Free Response** 

2019

DO NOT OPEN THIS BOOKLET UNTIL YOU ARE TOLD TO DO SO.

#### At a Glance

#### **Total Time**

45 minutes

#### Number of Questions

3

#### **Percent of Total Score**

50%

#### **Writing Instrument**

Either pencil or pen with black or dark blue ink

#### **Electronic Device**

Calculator allowed

#### Weight

The questions are weighted equally.

IMPORTANT Identification	on Information
PLEASE PRINT WITH PEN:  1. First two letters of your last name  First letter of your first name  2. Date of birth  Month Day Year  3. Six-digit school code	4. Unless I check the box below, I grant the College Board the unlimited right to use, reproduce, and publish my free-response materials, both written and oral, for educational research and instructional purposes. My name and the name of my school will not be used in any way in connection with my free-response materials. I understand that I am free to mark "No" with no effect on my score or its reporting.
	No, I do not grant the College Board these rights.

#### Instructions

The questions for Section II are printed in this booklet. You may use any blank space in the booklet for scratch work, but you must write your answers in the spaces provided for each answer. A table of information and lists of equations that may be helpful are in the booklet. Calculators, rulers, and straightedges may be used in this section.

All final numerical answers should include appropriate units. Credit for your work depends on demonstrating that you know which physical principles would be appropriate to apply in a particular situation. Therefore, you should show your work for each part in the space provided after that part. If you need more space, be sure to clearly indicate where you continue your work. Credit will be awarded only for work that is clearly designated as the solution to a specific part of a question. Credit also depends on the quality of your solutions and explanations, so you should show your work.

Write clearly and legibly. Cross out any errors you make; erased or crossed-out work will not be scored. You may lose credit for incorrect work that is not crossed out.

Manage your time carefully. You may proceed freely from one question to the next. You may review your responses if you finish before the end of the exam is announced.

#### ADVANCED PLACEMENT PHYSICS C TABLE OF INFORMATION

#### CONSTANTS AND CONVERSION FACTORS

Proton mass,  $m_p = 1.67 \times 10^{-27} \text{ kg}$ 

Neutron mass,  $m_n = 1.67 \times 10^{-27} \text{ kg}$ 

Electron mass,  $m_e = 9.11 \times 10^{-31} \text{ kg}$ 

Avogadro's number,  $N_0 = 6.02 \times 10^{23} \text{ mol}^{-1}$ 

Universal gas constant,  $R = 8.31 \text{ J/(mol \cdot K)}$ 

Boltzmann's constant,  $k_B = 1.38 \times 10^{-23} \text{ J/K}$ 

Electron charge magnitude,  $e = 1.60 \times 10^{-19} \text{ C}$ 

1 electron volt,  $1 \text{ eV} = 1.60 \times 10^{-19} \text{ J}$ 

Speed of light,  $c = 3.00 \times 10^8$  m/s

Universal gravitational

constant,

 $G = 6.67 \times 10^{-11} \left( \text{N} \cdot \text{m}^2 \right) / \text{kg}^2$ 

Acceleration due to gravity at Earth's surface,

o gravity  $g = 9.8 \text{ m/s}^2$ 

1 unified atomic mass unit,

Planck's constant,

 $1 \text{ u} = 1.66 \times 10^{-27} \text{ kg} = 931 \text{ MeV}/c^2$ 

 $h = 6.63 \times 10^{-34} \text{ J} \cdot \text{s} = 4.14 \times 10^{-15} \text{ eV} \cdot \text{s}$ 

 $hc = 1.99 \times 10^{-25} \text{ J} \cdot \text{m} = 1.24 \times 10^3 \text{ eV} \cdot \text{nm}$ 

Vacuum permittivity,

 $\varepsilon_0 = 8.85 \times 10^{-12} \text{ C}^2 / (\text{N} \cdot \text{m}^2)$ 

Coulomb's law constant,  $k = 1/(4\pi\varepsilon_0) = 9.0 \times 10^9 \text{ (N·m}^2)/\text{C}^2$ 

Vacuum permeability,

 $\mu_0 = 4\pi \times 10^{-7} \text{ (T-m)/A}$ 

Magnetic constant,  $k' = \mu_0/(4\pi) = 1 \times 10^{-7} \text{ (T-m)/A}$ 

1 atmosphere pressure,

 $1 \text{ atm} = 1.0 \times 10^5 \text{ N/m}^2 = 1.0 \times 10^5 \text{ Pa}$ 

UNIT SYMBOLS	meter,	m	mole,	mol	watt,	W	farad,	F
	kilogram,	kg	hertz,	Hz	coulomb,	C	tesla,	T
	second,	S	newton,	N	volt,	V	degree Celsius,	°C
	ampere,	A	pascal,	Pa	ohm,	Ω	electron volt,	eV
	kelvin,	K	joule,	J	henry,	Н		

PREFIXES				
Factor	Prefix	Symbol		
10 <sup>9</sup>	giga	G		
10 <sup>6</sup>	mega	M		
10 <sup>3</sup>	kilo	k		
$10^{-2}$	centi	c		
$10^{-3}$	milli	m		
$10^{-6}$	micro	μ		
10 <sup>-9</sup>	nano	n		
$10^{-12}$	pico	p		

VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES							
$\theta$	0°	30°	37°	45°	53°	60°	90°
$\sin \theta$	0	1/2	3/5	$\sqrt{2}/2$	4/5	$\sqrt{3}/2$	1
$\cos \theta$	1	$\sqrt{3}/2$	4/5	$\sqrt{2}/2$	3/5	1/2	0
$\tan \theta$	0	$\sqrt{3}/3$	3/4	1	4/3	$\sqrt{3}$	8

The following assumptions are used in this exam.

- I. The frame of reference of any problem is inertial unless otherwise stated
- II. The direction of current is the direction in which positive charges would drift.
- III. The electric potential is zero at an infinite distance from an isolated point charge.
- IV. All batteries and meters are ideal unless otherwise stated.
- V. Edge effects for the electric field of a parallel plate capacitor are negligible unless otherwise stated.

#### ADVANCED PLACEMENT PHYSICS C EQUATIONS

#### **MECHANICS**

$v_x = v_{x0} + a_x t$	a = acceleration
1 2	E = energy
$x = x_0 + v_{x0}t + \frac{1}{2}a_xt^2$	F = force
2 2 2 2 (2 2 2 )	f = frequency
$v_x^2 = v_{x0}^2 + 2a_x(x - x_0)$	h = height
$\sum \vec{r} = \vec{r}$	I = rotational inertia
$\sum F = F_{max}$	

$$\vec{a} = \frac{\sum F}{m} = \frac{F_{net}}{m}$$
 $J = \text{impulse}$ 
 $K = \text{kinetic energy}$ 
 $K = \text{spring constant}$ 

$$\vec{F} = \frac{d\vec{p}}{dt}$$
  $k = \text{spring constant}$   $\ell = \text{length}$ 

$$\vec{J} = \int \vec{F} \, dt = \Delta \vec{p} \qquad \qquad L = \text{angular momentum}$$
 
$$\vec{J} = \int \vec{F} \, dt = \Delta \vec{p} \qquad \qquad m = \text{mass}$$

$$\vec{p} = m\vec{v}$$
  $P = \text{power}$   $p = \text{momentum}$   $r = \text{radius or distance}$ 

$$\left| \vec{F}_f \right| \le \mu \left| \vec{F}_N \right| \qquad \qquad T = \text{ period}$$
 
$$t = \text{ time}$$

$$\Delta E = W = \int \vec{F} \cdot d\vec{r}$$

$$U = \text{potential energy}$$

$$v = \text{velocity or speed}$$

$$K = \frac{1}{2}mv^2$$
  $W = \text{work done on a system}$   
 $x = \text{position}$ 

$$P = \frac{dE}{dt}$$

$$\mu = \text{coefficient of friction}$$

$$\theta = \text{angle}$$

$$\tau = \text{torque}$$

$$P = \vec{F} \cdot \vec{v}$$
  $\omega = \text{angular speed}$   $\alpha = \text{angular acceleration}$ 

$$\Delta U_g = mg\Delta h$$
  $\phi = \text{phase angle}$   $\vec{F}_s = -k\Delta \vec{x}$ 

$$a_{c} = \frac{v^{2}}{r} = \omega^{2} r$$

$$U_{s} = \frac{1}{2} k (\Delta x)^{2}$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\alpha} = \frac{\sum \vec{\tau}}{I} = \frac{\vec{\tau}_{net}}{I}$$

$$x = x_{\text{max}} \cos(\omega t + \phi)$$

$$T = 2\pi - 1$$

$$U = \frac{2\pi}{I} = \frac{1}{I}$$

$$I = \int r^2 dm = \sum mr^2$$

$$T_{s} = 2\pi \sqrt{\frac{m}{k}}$$

$$T_{s} = 2\pi \sqrt{\frac{m}{k}}$$

$$T_{p} = 2\pi \sqrt{\frac{\ell}{g}}$$

$$v = r\omega$$
  $|\vec{F}_G| = \frac{Gm_1m_2}{r^2}$ 

$$K = \frac{1}{2}I\omega^2 \qquad U_G = -\frac{Gm_1m_2}{r}$$

$$\omega = \omega_0 + \alpha t$$

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

#### ELECTRICITY AND MAGNETISM

$$|\vec{F}_{E}| = \frac{1}{4\pi\varepsilon_{0}} \left| \frac{q_{1}q_{2}}{r^{2}} \right|$$
  $A = \text{area}$   $B = \text{magnetic field}$   $C = \text{capacitance}$   $d = \text{distance}$   $d =$ 

$$E_x = -\frac{dV}{dx}$$
  $I = \text{current}$   $J = \text{current density}$   $J = \text{inductance}$ 

$$\ell = \text{length}$$

$$\Delta V = -\int \vec{E} \cdot d\vec{r}$$

$$n = \text{number of loops of wire}$$

$$\text{per unit length}$$

$$V = \frac{1}{4\pi\varepsilon_0} \sum_{i} \frac{q_i}{r_i}$$

$$N = \text{number of charge carriers}$$

$$\text{per unit volume}$$

$$P = \text{power}$$

$$U_E = qV = \frac{1}{4\pi\varepsilon_0} \frac{q_1 q_2}{r}$$
  $Q = \text{charge}$   
 $q = \text{point charge}$   
 $R = \text{resistance}$ 

$$U = \text{potential or stored energy}$$
 $C = \frac{\kappa \varepsilon_0 A}{d}$ 
 $V = \text{electric potential}$ 
 $V = \text{velocity or speed}$ 
 $V = \text{potential}$ 
 $V = \text{potential or stored energy}$ 
 $V = \text{$ 

$$\Phi = \text{flux}$$

$$\kappa = \text{dielectric constant}$$

$$\frac{1}{C_s} = \sum_{i} \frac{1}{C_i}$$

$$\vec{F}_M = q\vec{v} \times \vec{B}$$

$$\frac{\vec{c}}{C_S} = \sum_{i} \frac{\vec{c}}{C_i} \qquad \vec{F}_M = q\vec{v} \times \vec{B}$$

$$I = \frac{dQ}{dt} \qquad \oint \vec{B} \cdot d\vec{\ell} = \mu_0 I$$

$$U_C = \frac{1}{2}Q\Delta V = \frac{1}{2}C(\Delta V)^2 \qquad d\vec{B} = \frac{\mu_0}{4\pi} \frac{I \, d\vec{\ell} \times \hat{r}}{r^2}$$

$$R = \frac{\rho \ell}{A}$$
  $\vec{F} = \int I \ d\vec{\ell} \times \vec{B}$   $\vec{E} = \rho \vec{J}$   $B_s = \mu_0 n I$ 

$$I = Nev_d A \qquad \Phi_B = \int \vec{B} \cdot d\vec{A}$$

$$I = \frac{\Delta V}{R} \qquad \qquad \mathcal{E} = \oint \vec{E} \cdot d\vec{\ell} = -\frac{d\Phi_B}{dt}$$

$$R_{s} = \sum_{i} R_{i} \qquad \qquad \varepsilon = -L \frac{dI}{dt}$$

$$\frac{1}{R_p} = \sum_i \frac{1}{R_i} \qquad U_L = \frac{1}{2}LI^2$$

$$P = I\Delta V$$

#### GEOMETRY AND TRIGONOMETRY

#### Rectangle

A = area

A = bh

C = circumference

Triangle

V = volumeS =surface area

b = base

 $A = \frac{1}{2}bh$ 

Circle

h = height

 $A = \pi r^2$ 

 $\ell = length$ 

 $C = 2\pi r$ 

w = widthr = radius

s = arc length

 $s = r\theta$ 

 $\theta$  = angle

#### Rectangular Solid

$$V = \ell w h$$

Cylinder

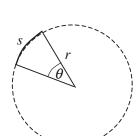
$$V = \pi r^2 \ell$$

$$S = 2\pi r\ell + 2\pi r^2$$

Sphere

$$V = \frac{4}{3}\pi r^3$$

$$S = 4\pi r^2$$



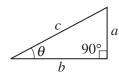
#### Right Triangle

$$a^2 + b^2 = c^2$$

$$\sin\theta = \frac{a}{c}$$

$$\cos\theta = \frac{b}{c}$$

$$\tan \theta = \frac{a}{b}$$



#### **CALCULUS**

$$\frac{df}{dx} = \frac{df}{du}\frac{du}{dx}$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(e^{ax}) = ae^{ax}$$

$$\frac{d}{dx}(\ln ax) = \frac{1}{x}$$

$$\frac{d}{dx}[\sin(ax)] = a\cos(ax)$$

$$\frac{d}{dx}[\cos(ax)] = -a\sin(ax)$$

$$\int x^n \, dx = \frac{1}{n+1} x^{n+1}, \, n \neq -1$$

$$\int e^{ax} dx = \frac{1}{a} e^{ax}$$

$$\int \frac{dx}{x+a} = \ln|x+a|$$

$$\int \cos(ax) dx = \frac{1}{a} \sin(ax)$$

$$\int \sin(ax) dx = -\frac{1}{a} \cos(ax)$$

#### **VECTOR PRODUCTS**

$$\vec{A} \cdot \vec{B} = AB \cos \theta$$

$$|\vec{A} \times \vec{B}| = AB\sin\theta$$

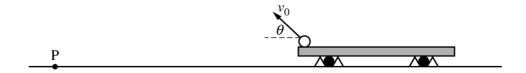
#### PHYSICS C: MECHANICS

#### **SECTION II**

#### Time—45 minutes

3 Questions

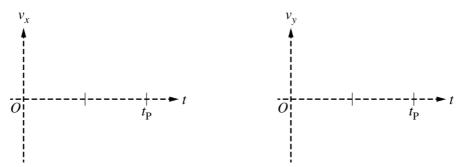
**Directions:** Answer all three questions. The suggested time is about 15 minutes for answering each of the questions, which are worth 15 points each. The parts within a question may not have equal weight. Show all your work in this booklet in the spaces provided after each part.

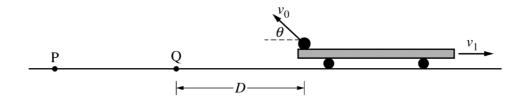


Note: Figure not drawn to scale.

- A projectile is launched from the back of a cart of mass m that is held at rest, as shown above. At time t = 0, the projectile leaves the cart with speed v<sub>0</sub> at an angle θ above the horizontal. The projectile lands at point P.
   Assume that the starting height of the projectile above the ground is negligible compared to the maximum height reached by the projectile and the horizontal distance traveled.
  - (a) Derive an expression for the time  $t_P$  at which the projectile reaches point P. Express your answer in terms of  $v_0$ ,  $\theta$ , and physical constants, as appropriate.

(b) On the axes below, sketch the horizontal component  $v_x$  and the vertical component  $v_y$  of the velocity of the projectile as a function of time t from t = 0 until  $t = t_p$ . Explicitly label the vertical intercepts with algebraic expressions.





Note: Figure not drawn to scale.

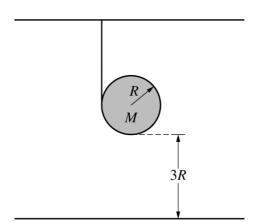
The projectile is again launched from the same position, but with the cart traveling to the right with speed  $v_1$  relative to the ground, as shown above. The projectile again leaves the cart with speed  $v_0$  relative to the cart at an angle  $\theta$  above the horizontal, and the projectile lands at point Q, which is a horizontal distance D from the launching point. Express your answers in terms of  $v_0$ ,  $\theta$ , and physical constants, as appropriate.

- (c) Give a physical reason why the projectile lands at point Q, which is not as far from the launch position as point P is, and explain how that physical reason affects the flight of the projectile.
- (d) Derive an expression for  $v_1$ . Express your answer in terms of  $v_0$ ,  $\theta$ , D, and physical constants, as appropriate.

After the launch, the cart's speed is  $v_2$ . Beginning at time t = 0, the cart experiences a braking force of F = -bv, where b is a positive constant with units of kg/s and v is the speed of the cart. Express your answers to the following in terms of m, b,  $v_2$ , and physical constants, as appropriate.

(e)

- i. Using Newton's second law, write but DO NOT solve a differential equation that represents the motion of the cart while it experiences the braking force.
- ii. Show that the speed v(t) of the cart as a function of time is given by the equation  $v(t) = v_2 e^{-bt/m}$ .
- iii. Derive an expression for the distance the cart travels from t = 0 until the time it comes to a stop.



- 2. A thin uniform disk of mass M and radius R has a string wrapped around its edge and attached to the ceiling. The bottom of the disk is at a height 3R above the floor, as shown above. The disk is released from rest. The rotational inertia of a disk around its center is  $I = MR^2/2$ .
  - (a) On the circle below that represents the disk, draw and label the forces (not components) that act on the disk. Each force must be represented by a distinct arrow starting on, and pointing away from, the disk, beginning at the point where the force is exerted on the disk. The dot is at the center of the disk.



(b) When released from rest, the disk falls and the string unwinds. The force the string exerts on the disk is  $F_T$ , and the gravitational force exerted on the disk is  $F_g$ . Which of the following expressions correctly relates

 ${\it F_T}$  and  ${\it F_g}$  as the disk falls?

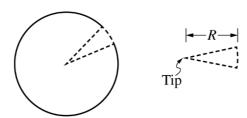
$$F_T < F_g$$
  $F_T = F_g$   $F_T > F_g$ 

$$F_T = F_T$$

$$F_T > F_g$$

Justify your answer.

<ul><li>(c) Express all answers in terms of M, R, and physical constants, as appropriate.</li><li>i. Derive an expression for the acceleration a of the disk as it falls.</li></ul>	
ii. Derive an expression for the time $\Delta t$ that it takes the disk to reach the ground.	
iii. Derive an expression for the rotational kinetic energy $K_{\rm rot}$ of the disk at the instant it reaches the ground.	
Question 2 continues on the next page.	



Note: Figure not drawn to scale.

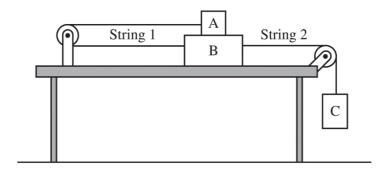
(d) A very narrow wedge is cut out of the thin uniform disk of mass M, as shown above. If r is the distance from the tip of the wedge, then the linear mass density of the wedge can be expressed as follows:

$$\lambda\left(r\right) = \frac{Mr}{25R^2}.$$

i. Using integral calculus, derive an expression for the rotational inertia of the wedge around its tip.

ii. Derive an expression for the rotational inertia of the modified disk (i.e., the disk after the narrow wedge is cut out) around its original center.

### THIS PAGE MAY BE USED FOR SCRATCH WORK.



3. Three blocks are connected by strings that pass over pulleys of negligible mass. Block B is on a level, horizontal surface of negligible friction. Block A is on top of block B. String 1 connects blocks A and B. The coefficients of static and kinetic friction between blocks A and B are  $\mu_s$  and  $\mu_k$ , respectively. Block C is hanging over the end of the table and is attached to block B by string 2, as shown above. The masses of blocks A, B, and C are  $m_A$ ,  $m_B$ , and  $m_C$ , respectively. When block C is released, the system remains at rest.

(a)

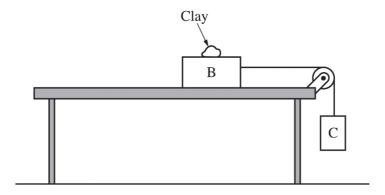
i. On the dot below, which represents block A, draw and label the forces (not components) that act on block A. Each force must be represented by a distinct arrow starting on, and pointing away from, the dot.



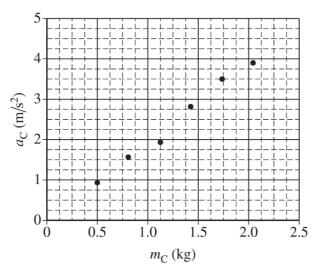
ii. On the dot below, which represents block B, draw and label the forces (not components) that act on block B. Each force must be represented by a distinct arrow starting on, and pointing away from, the dot.

#### Block B

(b) Derive an expression for the maximum value for  $m_C$  at which the blocks will remain at rest. Express all algebraic answers in terms of  $\mu_s$ ,  $\mu_k$ ,  $m_A$ ,  $m_B$ ,  $m_C$ , and physical constants, as appropriate.



The setup is modified, as shown in the figure above. Block A and one of the pulleys are removed, and block B remains on the table. There is still negligible friction between block B and the table. A lump of clay is added to block B. The students use Newton's second law to derive an equation for the acceleration  $a_{\rm C}$  of block C. The acceleration is given by the equation  $a_{\rm C} = m_{\rm C} g/m_{\rm tot}$ , where  $m_{\rm tot}$  is the combined mass of the clay and the two blocks. Students use the setup shown above to experimentally determine the acceleration g due to gravity. In each trial, a student moves a small amount of clay from block B to block C and then releases the blocks from rest, recording the new values of  $m_{\rm C}$  and  $a_{\rm C}$ . The total mass of the clay and the two blocks is  $m_{\rm tot} = 5.0$  kg. The graph below shows  $a_{\rm C}$  as a function of  $m_{\rm C}$ , where  $m_{\rm C}$  is now the combined mass of block C and the mass of clay added to block C.



(c)

- i. Draw a best-fit line to the data points in the graph above.
- ii. Use the best-fit line from part (c)(i) to calculate an experimental value for the acceleration g due to gravity.

(d) If the mass of the pulley in part (c) is significant, would the experimental value of *g* be greater than, less than, or equal to the value calculated in part (c)(ii)?

\_\_\_\_ Greater than

\_\_\_\_ Less than

\_\_\_\_ Equal to

Justify your answer.

A different group of students repeats the experiment, but instead of moving clay from block B to block C, they just remove a small amount of clay from block B and set it aside, away from the setup. The equation  $a_{\rm C} = m_{\rm C} g/m_{\rm tot}$  still applies to the new experiment.

(e) In order to provide a straight-line graph that can be used to determine an experimental value for g, what two quantities should the students now graph? Check all that apply.

 $a_c$  vs  $\frac{1}{m_{tot}}$ 

 $\underline{\phantom{a}} a_c \text{ vs } m_{tot}$ 

 $\underline{\qquad} a_c \text{ vs } \frac{m_c}{m_{tot}}$ 

 $\underline{\phantom{a}}$   $a_c$  vs  $m_C$ 

 $\underline{\qquad} m_c \text{ vs } \frac{1}{m_{tot}}$ 

Justify your answer.

#### STOP

#### **END OF EXAM**

THE FOLLOWING INSTRUCTIONS APPLY TO THE COVERS OF THE SECTION II BOOKLET.

- MAKE SURE YOU HAVE COMPLETED THE IDENTIFICATION INFORMATION AS REQUESTED ON THE FRONT <u>AND</u> BACK COVERS OF THE SECTION II BOOKLET.
- CHECK TO SEE THAT YOUR AP NUMBER LABEL APPEARS IN THE BOX ON THE COVER.
- MAKE SURE YOU HAVE USED THE SAME SET OF AP NUMBER LABELS ON <u>ALL</u> AP EXAMS YOU HAVE TAKEN THIS YEAR.

# Answer Key for AP Physics C: Mechanics Practice Exam, Section I

Question 1: D	Question 19: A
Question 2: C	Question 20: C
Question 3: D	Question 21: E
Question 4: A	Question 22: E
Question 5: D	Question 23: D
Question 6: D	Question 24: D
Question 7: B	Question 25: D
Question 8: B	Question 26: C
Question 9: E	Question 27: E
Question 10: B	Question 28: C
Question 11: B	Question 29: D
Question 12: B	Question 30: D
Question 13: A	Question 31: B
Question 14: A	Question 32: A
Question 15: C	Question 33: E
Question 16: A	Question 34: A
Question 17: C	Question 35: D
Question 18: C	

# Multiple-Choice Section for Physics C: Mechanics 2019 Course Framework Alignment and Rationales

Skill		Learning Objective	Topic
4.D		CHA-1.C	Kinematics - Motion in One Dimension
(A)	t = 8s to indicate	option uses the lines of the sate that the cars are at the sate a under the curve must be	time location at $t = 8$ s.
(B)	the distance bet	option uses the difference in ween the cars at $t = 8s$ . Ho sed to analyze this situation	wever, the area under the
(C)	as the distance b	option uses the displacement between the cars at $t = 8s$ . Due used to analyze this situal	However, the area under
(D)	$t = 8$ s, Car A Area = $\frac{1}{2}bh$ = Car B has a dis	ea under the velocity curve has a displacement of $(\frac{1}{2})(8s)(12 \text{ m/s}) = 48 \text{ m}$ in placement of Area $=\frac{1}{2}bh$ direction. Therefore, the dis 6 m.	the positive direction, and $= (\frac{1}{2})(8s)(12 \text{ m/s}) = 48 \text{ m}$
(E)		option uses $d = vt$ and sets ea under the curve must be	

Skill		Learning Objective	Topic
6.C		CHA-1.B	Kinematics - Motion in One Dimension
(A)		option is the second derivates instead of $t = 3$ s.	ive of position but
(B)		option is the second derivated is instead of $t = 3s$ and additional second derivative and additional second derivative and the second derivative and derivative and the second derivative and derivati	-
(C)	Correct. This option uses $a = \frac{d^2y}{dt^2} = \frac{d^2}{dt^2}(\alpha t^3 - \beta t + \phi) = \frac{d}{dt}(3\alpha t^2 - \beta) = 6\alpha t.$ Substituting $t = 3.0$ s yields $a = 6\alpha t = (6)(1)(3) = 18 \text{ m/s}^2$ .		
(D)	Incorrect. This option solves for the speed, instead of the acceleration, at $t = 3$ s.		
(E)	Incorrect. This option solves for the speed, instead of the acceleration, at $t = 3$ s. It also does not include the $\beta$ term when solving for speed.		

Skill		Learning Objective	Topic	
7.A		CHA-2.C	Kinematics - Motion in Two Dimensions	
(A)	same, the stones	Incorrect. This option assumes that since the initial speeds are the same, the stones reach the ground at the same time, ignoring the different directions for the initial velocities.		
(B)	same, the stones different direction	option assumes that since the ground at the same one for the initial velocities, moving downward initially, speed.	me time, ignoring the . It also assumes that since	
(C)	because t is sho	option can be obtained by interfer stone A, stone B of the hitting the ground.		
(D)	<b>Correct.</b> Both stone A and stone B initially have the same potential energy $U_i$ and kinetic energy $K_i$ . Both stones therefore have the same $K_f$ at ground level, when $U_f = 0$ . Substituting into conservation of energy to solve for the speeds of the stones when $U_i + K_i = U_f + K_f$			
	they reach the ground yields $mgh + \frac{1}{2}mv_0^2 = 0 + \frac{1}{2}mv_f^2$ ; thus, $v_f = \sqrt{v_0^2 + 2gh}$ because both stones have the same initial speed, they will both have the same speed when they reach the ground.			
(E)	•		B. For stone A, the ertical $v_0$ , yielding ertical $gt$ would be added ding $v_f = \sqrt{v_0^2 + (gt)^2}$ .	

Skill		Learning Objective	Topic
1.D		INT-2.C	Circular Motion
(A)		rection of velocity is tangen ch the object is moving.	t to the circle and in the
(B)	Incorrect. This option can be obtained by using the vector sum of the car's velocity and the centripetal acceleration. It is not the direction of the car's velocity.		· ·
(C)	Incorrect. This option is the direction of centripetal acceleration, not the direction of the car's velocity.		ntripetal acceleration, not
(D)		option is the vector sum of a centripetal acceleration. It	
(E)	Incorrect. This direction of the	option is the direction of lin	near acceleration, not the

Skill		Learning Objective	Topic
1.D		INT-2.C	Circular Motion
(A)	Incorrect. This acceleration.	option is the direction of the	e car's velocity, not its
(B)	Incorrect. This option is the vector sum of the velocity and the centripetal acceleration. It is not the car's acceleration.		•
(C)	Incorrect. This option is the direction of the car's centripetal acceleration, not its acceleration.		e car's centripetal
(D)	<b>Correct</b> . The direction of acceleration is the direction of the vector sum of the linear acceleration and the centripetal acceleration.		
(E)	Incorrect. This not its accelerat	option is the direction of the	e car's linear acceleration,

Skill		Learning Objective	Topic
6.B		INT-2.A	Circular Motion
(A)		option is the difference betw	
	be added as vect	nd linear accelerations. The ors.	e two accelerations should
(B)	Incorrect. This option is the magnitude of the centripetal acceleration. It should be added as a vector to the car's linear acceleration.		-
(C)	Incorrect. This option is the magnitude of the linear acceleration. It should be added as a vector to the car's centripetal acceleration.		
(D)	<b>Correct</b> . The magnitude of acceleration is determined by adding the linear and centripetal accelerations as vectors. The linear acceleration is $a_L = -1.20 \text{m/s}^2$ . The centripetal acceleration is given by		
	substituting into the equation $a_C = \frac{v^2}{r} = \frac{(36.0 \text{m/s})^2}{(1440 \text{m})} = 0.90 \text{m/s}^2$ . Adding the two accelerations as vectors yields $a = \sqrt{a_L^2 + a_C^2} = \sqrt{(-1.20 \text{m/s}^2)^2 + (0.90 \text{m/s}^2)^2} = 1.50 \text{m/s}^2$ .		
(E)	Incorrect. This	option adds the magnitudes	of the centripetal and

Skill		Learning Objective	Topic
4.D		CHA-1.C	Kinematics - Motion in One Dimension
(A)	Incorrect. This acceleration.	option is the maximum acco	eleration, not the average
(B)	<b>Correct</b> . The average acceleration is the average rate of velocity change over a time interval. For a velocity-time graph, that will be the slope of the straight line connecting the starting and ending points. Solving for the slope yields $a_{\text{avg}} = \text{slope} = \frac{(2 \text{m/s} - 6 \text{m/s})}{(10 \text{s} - 0 \text{s})} = 0.40 \text{m/s}^2.$		time graph, that will be starting and ending
(C)		option calculates the correction, but it has the wrong s	· ·
(D)	Incorrect. This option is the final acceleration, not the average acceleration.		on, not the average
(E)	Incorrect. This option is the maximum acceleration, not the average acceleration. This option also has the wrong sign.		· ·

Skill		Learning Objective	Topic
4.D		CHA-1.C	Kinematics - Motion in One Dimension
(A)		option uses the area under the curve to determine the out it makes the area from $t = 0$ to $t = 3$ s negative instead of	
(B)	over an interval graph's $\Delta x$ valu	efinition, the average velocity is the average rate of position change al. Mathematically, this is $\frac{\Delta x}{\Delta t}$ . Therefore, using the velocity llue, which is the sum of the signed areas under the curve, $\frac{1}{2}(1s)(-2m/s)+\frac{1}{2}(2s)(-2m/s)+\frac{1}{2}(2s)(2m/s)$	
(C)	displacement, b	scorrect. This option uses the area under the curve to determine the splacement, but it makes the area from $t = 3s$ to $t = 8s$ positive instead of egative and the area from $t = 8s$ to $t = 10s$ negative instead of positive.	
(D)		ect. This option uses the area under the curve to determine the cement, but it makes all the areas positive, and the area from $t = 3s$ to is negative.	
(E)	Incorrect. This option uses the equation for constant acceleration, $\frac{1}{2}(v_0 + v_f)$ , to calculate the average velocity. However, the acceleration, which is the slope of this graph, is not constant for this graph.		

Skill		Learning Objective	Topic
7.C		INT-1.E	Newton's Laws of Motion - First and Second Laws
(A)	Incorrect. Object exerted on them	cts at rest tend to stay at rest n is zero.	t only when the net force
(B)	always in the direction opposes	option assumes that static for rection opposing the object the potential motion between vays the direction opposing	's motion. However, static een the two surfaces,
(C)	Incorrect. This option assumes that kinetic friction on an object is always in the direction opposite the object's motion. However, kinetic friction opposes the motion between the two surfaces, which is not always the direction opposing the object's motion.		
(D)	Incorrect. The frictional force would not even momentarily be static friction, because, the moment $\vec{F}$ is applied to the lower block, the lower block instantly accelerates. If static friction caused this acceleration, then the top block would move together with the bottom block. As described in the problem, the blocks do not move together; thus, it is not static friction between the top block and bottom block.		to the lower block, the iction caused this re together with the the blocks do not move
(E)	fast as the botto friction from the together, the fric	p block accelerates to the rig m block. The force exerted e bottom block. Since the bl ction is kinetic friction. Since t, the top block will land to	on the top block is locks do not move ce the blocks are moving

Skill		Learning Objective	Topic
7.A		INT-1.H	Newton's Laws of Motion - First and Second Laws
(A)	increases as the sphere is speeding	option shows that the magn sphere gets closer to the gro ng up, the resistive force in a decrease as the stone gets o	ound. However, if the creases, and the net force
(B)	force will always and the accelera magnitude of th magnitude of th fallen each secon up, the resistive	e sphere never reaches terminal velocity, the resistive ays be less than the force of gravity; thus, the net force ration will always be downward. Therefore, the the sphere's velocity will always be increasing. If the the sphere's velocity is always increasing, the distance cond will be increasing. Also, if the sphere is speeding we force increases, and the net force and acceleration e stone gets closer to the ground.	
(C)	magnitude of ve thus, if the magn	ncorrect. This option can be obtained by not recognizing that the nagnitude of velocity is the same as the distance fallen each second; hus, if the magnitude of the velocity is increasing, the distance fallen ach second must also increase.	
(D)	increases as the sphere is speeding and acceleration also indicates the fallen each second always be less the acceleration will	correct. This option shows that the magnitude of acceleration creases as the sphere gets closer to the ground. However, if the here is speeding up, the resistive force increases, and the net force d acceleration decrease as the stone gets closer to the ground. It to indicates that the magnitude of the velocity and the distance len each second are decreasing. However, the resistive force will ways be less than the force of gravity; thus, the net force and the celeration will always be downward; thus, the magnitude of the here's velocity and the distance fallen each second are increasing.	
(E)	decreasing. How force of gravity;	option indicates that the may wever, the resistive force will thus, the net force and the s, the magnitude of the sphe	l always be less than the acceleration will always be

Skill		Learning Objective	Topic
6.C		INT-1.C	Newton's Laws of Motion - First and Second Laws
(A)	Incorrect. This	option is the acceleration of	the object, not the force.
(B)	Correct. The ac	celeration is the derivative	of the velocity,
	$a = \frac{dv}{dt} = \frac{d}{dt} \left( \alpha e^{-\beta t} \right) = -\beta \alpha e^{-\beta t}.$ Substituting into an equation fo		
	Newton's second law yields $F_{\text{net}} = ma = m\left(-\beta\alpha e^{-\beta t}\right)$ $F_{\text{net}} = (0.5 \text{ kg})\left(-3\text{s}^{-1}\right)(2 \text{ m/s})e^{\left(-3\text{s}^{-1}\right)t} = -3e^{-3t}$		
(C)	Incorrect. This option is the exponential part of the equation for force. It does not include the coefficient.		
(D)	Incorrect. This option is the velocity of the object, not the force.		
(E)	Incorrect. This taking the deriv	option integrates the equati ative.	on for velocity instead of

Skill		Learning Objective	Topic	
6.C		INT-4.C	Work-Energy Theorem	
(A)		Incorrect. This option uses the work-energy theorem to calculate the energy dissipated but does not square the initial speed.		
(B)	<b>Correct.</b> The object will eventually come to rest; thus, the energy dissipated will be equal to initial kinetic energy. Using $t=0$ and substituting into the kinetic energy equation yields $E = \Delta K = \frac{1}{2}m(v_f^2 - v_i^2) = -\frac{1}{2}m(0 - v_i^2)$ $E = -\frac{1}{2}m(\alpha e^{-\beta t})^2 = -\left(\frac{1}{2}\right)(0.50\text{kg})\left[(2\text{m/s})(e^0)\right]^2 = 1\text{J}$			
(C)	Incorrect. This option uses the work-energy theorem to calculate the energy dissipated but does not include the mass of the object.			
(D)	Incorrect. This option uses the work-energy theorem to calculate the energy dissipated but sets the kinetic energy equal to the square of the function for speed.			
(E)		option indicates that the object energy dissipated will be i		

Skill		Learning Objective	Topic
6.C		CON-4.F	Conservation of Linear Momentum, Collisions
(A)	is a vector; thus, analyzed independentum in the managementum in the management $m_A v_{Ai} = (m_A + m_A v_{Ai}) = \frac{m_A v_{Ai}}{(m_A + m_A v_{Bi})}$ vertical direction $m_B v_{Bi} = (m_A + m_A v_{Bi}) = \frac{m_B v_{Bi}}{(m_A + m_A v_{Bi})}$ into the trigonorm	$\frac{(3.05 \text{kg})(2.5 \text{m/s})}{(3.05 \text{kg} + 2.10 \text{kg})} =$ n yields	directions can be conservation of ds and in the 1.48 m/s Substituting yields
(B)	Incorrect. This option uses the initial velocities instead of the final velocities to find the angle.		
(C)	Incorrect. This option indicates that the final direction is the average of the initial directions of the two carts. However, this would only be the result if the two carts had equal initial momentums.		
(D)	Incorrect. This option uses the initial velocities instead of the final velocities to find the angle. Also, it reverse the two components in the equation for tangent.		
(E)		option calculates the final voet two components in the eq	•

Skill		Learning Objective	Topic
6.B		INT-4.C	Work-Energy Theorem
(A)	Correct. Setting	the energy dissipated equa	l to the change in kinetic
	E	$= fd = \Delta K = \frac{1}{2}m(v_f^2 - v_f^2)$	$\binom{2}{i} = \frac{1}{2}m(0-v_i^2)$
	energy yields -	$umgd = -\frac{1}{2}mv_i^2$	
	$\mu = \frac{v_i^2}{2gd} = \frac{(0.6 \text{m/s})^2}{2(9.81 \text{m/s}^2)(0.24 m)} = 0.08$		
(B)	Incorrect. This option sets the energy dissipated equal to the change in kinetic energy but does not square the speed of the carts.		
(C)	Incorrect. This option sets the energy dissipated equal to the change in kinetic energy but does not include the one-half from the kinetic energy equation.		
(D)	Incorrect. This option sets the energy dissipated equal to the change in kinetic energy but does not square the speed of the carts. It also does not include the one-half from the kinetic energy equation.		
(E)		option sets the energy dissip but does not include g in t	

Skill		Learning Objective	Topic
5.E		CON-2.C	Conservation of Energy
(A)	Incorrect. This of energy, at $x = 0$	option is the elastic potential.	al energy, not the kinetic
(B)	Incorrect. This	option is the kinetic energy	at $x = 0$ .
(C)	<b>Correct.</b> The kinetic energy at $x=0$ is equal to the difference of the initial elastic potential energy of the spring-block system and the energy dissipated by friction. Substituting into an energy equation $U_{Si} + fd = K_f$ yields $K_f = \frac{1}{2}kA^2 - fd = \frac{1}{2}kx_0^2 - \mu m dx_0$		
(D)	Incorrect. This option calculates the energy dissipated by friction from the initial position to the position where the block stops, $x = -\frac{1}{2}x_0$ .		
(E)	Incorrect. This option calculates the energy dissipated by friction from the initial position to a position equal to the amplitude on the negative side of equilibrium where $x = x_0$ .		

Skill		Learning Objective	Topic
5.E		CON-2.C	Conservation of Energy
(A)		the energy dissipated by free elastic potential energy of	-
	E = fd =	$= U_{Sf} - U_{Si} = \frac{1}{2}k\left(-\frac{1}{2}x_0\right)^2$	$(x^2 - \frac{1}{2}k(x_0)^2)$
	yields $\mu mgd =$	$\mu mg\left(\frac{3}{2}x_0\right) = \frac{3}{8}kx_0^2$	
	$\mu = \frac{kx_0^2}{4mg}$	-	
(B)	Incorrect. This option substitutes into the energy equation but sets the final elastic potential energy equal to zero instead of using the		
	elastic potential energy when the block is at $x = -\frac{1}{2}x_0$ .		
(C)	Incorrect. This option substitutes into the energy equation but sets		
	the distance moved by the block equal to $\frac{1}{2}x_0$ instead of $\frac{3}{2}x_0$ .		
(D)	Incorrect. This option substitutes into the energy equation but sets the final elastic potential energy equal to zero instead of using the		
	elastic potential energy when the block is at $x = -\frac{1}{2}x_0$ . It also does		
	not include the one-half in the elastic potential energy equation.		
(E)	Incorrect. This option substitutes into the energy equation but sets the final elastic potential energy equal to zero instead of using the		
	elastic potential	energy when the block is at	$x = -\frac{1}{2}x_0$ . It also does
	not include the	one-half in the elastic poten	itial energy equation and
	includes the one	e-half on the energy lost side	e of the equation.

Skill		Learning Objective	Topic
5.A		INT-8.D	Simple Harmonic Motion, Springs, and Pendulums
(A)	Incorrect. In this option, the spring force is in the same direction as the position of the block and is in the same direction as the friction when $x > 0$ .		
(B)	Incorrect. In this option, the spring force is in the same direction as the position of the block.		
(C)	<b>Correct</b> . Substituting into a Newton's second law equation yields $F_{net} = F_S + f = ma$ $m\frac{d^2x}{dt^2} = -kx + \mu mg$		
(D)	Incorrect. In this option, the spring force is in the same direction as the friction when $x > 0$ .		
(E)	Incorrect. In thi	s option, the effect of friction	on is ignored.

Skill		Learning Objective	Topic
5.E		CON-4.A	Conservation of Linear Momentum, Collisions
(A)	Incorrect. This option uses conservation of energy going up the hill to solve for $v_f$ instead of using conservation of momentum for the collision. It also omits the one-half in the kinetic energy equation.		
(B)	Incorrect. This option uses the kinematics equation for going up the hill to solve for the velocity at a height $h$ up the hill. However, $v_f$ is the final speed for the collision, not the final speed going up the hill to a height $h$ .		
(C)	<b>Correct.</b> Substituting into the conservation of momentum equation $p_i = p_f$ for the collision yields $mv_i = (m + M)v_f$ . $v_f = \frac{m}{(m + M)}v_i$		
(D)	Incorrect. This option substitutes into the conservation of momentum equation but does not include the mass of the projectile in the final momentum.		
(E)	Incorrect. This option substitutes into the conservation of momentum equation but uses the mass of the block instead of the mass of the projectile for the initial momentum. It also does not include the mass of the block in the final momentum.		

Skill		Learning Objective	Topic
5.E		CON-2.C	Conservation of Energy
(A)		gf	0, 1
(B)	Incorrect. This option substitutes into the conservation of energy equation but uses $h^2$ for gravitational potential energy instead of $h$ .		
(C)	Incorrect. This option substitutes into the conservation of energy equation but only uses the mass of the block for the initial kinetic energy and only uses the mass of the projectile for the final potential energy.		
(D)	Incorrect. This option substitutes into the conservation of energy equation but finds the reciprocal of the correct answer.		
(E)	equation but fin	option substitutes into the c ds the reciprocal of the cor peed in the kinetic energy e	rect answer. It also does

Skill		Learning Objective	Topic
6.A		INT-5.B	Impulse and Momentum
(A)	Incorrect. This option takes the derivative of the force instead of integrating the equation for the force.		
(B)	Incorrect. This option substitutes into the equation for the net force instead of first integrating the equation.		equation for the net force
(C)	<b>Correct.</b> Integrating the equation for the net force and substituting $J = \Delta p = \int F dt = \int \left(Kt^2 + \tau\right) dt$ the given values yields $\Delta p = \int_{t=0}^{t=3} \left(t^2 + 1\right) = \left[\frac{t^3}{3} + t\right]_{t=0}^{t=3}.$ $\Delta p = \left(\frac{1}{3}(3)^3 + 3\right) - 0 = 12 \text{kg} \cdot \text{m/s}$		
(D)	Incorrect. This option integrates the equation for the net force, but it does not divide the terms by the new powers on the variables.		
(E)	Incorrect. The values of momentum are not needed to determine the change in momentum because the change in momentum can be determined by integrating the equation for the net force.		

Skill		Learning Objective	Topic
7.A		CON-4.E	Conservation of Linear Momentum, Collisions
(A)	Incorrect. Only	if $m_{cart A} < m_{cart B}$ would c	art A move off to the left.
(B)	Incorrect. Only	if $m_{cartA} < m_{cartB}$ would c	art A move off to the left.
	Moreover, cart	B would not remain station	nary. Even if
	$m_{cart A} \ll m_{cart B}$ , the collision would give cart B a little velocity t		cart B a little velocity to
	the right.		
(C)	Incorrect. Only if $m_{cart A} = m_{cart B}$ would cart A be stopped by the		
	collision.		
(D)	Incorrect. The carts would be stuck together only if the collision was		
	inelastic, not elastic.		
(E)	Correct. For elastic collisions, when an object with a larger mass		
	collides with a stationary object that has a smaller mass, both objects		
	will move in the direction of motion of the first object. In elastic		first object. In elastic
	collision, the objects do not stick together; thus, the carts will move		thus, the carts will move
	to the right and	will not be stuck together.	

Skill		Learning Objective	Topic
5.E		INT-5.B	Impulse and Momentum
(A)	Incorrect. This option indicates that the net impulse exerted on the ball is zero because the magnitude of the ball's momentum does not change during the collisions with the floor. However, this does not take into account the change in direction of the ball's momentum.		
(B)	floor instead of include the one-	option solves for the impuls during the collision with the chalf in the kinetic energy ed ball when it reaches the floo	e floor. It also does not quation when solving for
(C)	Incorrect. This option solves for the impulse as the ball falls to the floor instead of during the collision with the floor.		
(D)	Incorrect. This option can result from a math error, simplifying $2m\sqrt{2gh}$ ) as $m\sqrt{4gh}$ ).		
(E)	<b>Correct</b> . The net impulse is the change in momentum of the ball during its collision with the floor. First, substituting into the conservation of energy equation to calculate the speed of the ball $K_i = U_{gf}$		
	when it reaches the floor yields $\frac{1}{2}mv_i^2 = mgh$ . The ball returns to $v = \sqrt{2gh}$ the same height when it leaves the floor; thus, the final speed for the ball during the collision with the floor is the same as the speed when		
	ball during the collision with the floor is the same as the speed when the ball reaches the floor, but it will be moving in the opposite direction. Therefore, one of the velocities must be negative. Then, substituting into the equation for change in momentum yields $\Delta p = p_f - p_i = m(v_f - v_i)$ $\Delta p = m(\sqrt{2gh} - (-\sqrt{2gh}))$ . $\Delta p = m(2\sqrt{2gh}) = m\sqrt{8gh}$		

Skill		Learning Objective	Topic
7.A		INT-7.E	Rotational Dynamics and Energy
(A)	Incorrect. This sphere.	option ignores the translation	onal kinetic energy of the
(B)	Incorrect. This sphere.	option ignores the rotationa	al kinetic energy of the
(C)		e the sphere will have both ic energy at the bottom of the the equal.	
(D)	Correct. The mechanical energy of the sphere-Earth system will be conserved as the sphere rolls down the incline; thus, the kinetic energy of the sphere at the bottom of the ramp must be equal to the potential energy of the sphere-Earth system when the sphere is at the top of the ramp, and the kinetic energy of the sphere is the sum of its translational kinetic energy and rotational kinetic energy.		
(E)		e is no energy lost due to fri ecause the sphere rolls with	•

Skill		Learning Objective	Topic
5.A		CON-5.D	Angular Momentum and Its Conservation
(A)		option substitutes into consumes $L = mR_{total}\omega$ instead	· ·
(B)		option substitutes into consumes $L = m\omega$ instead of $L$	· ·
(C)	Incorrect. This option substitutes into conservation of angular momentum but uses $L = mR_{avg}\omega$ instead of $L = I\omega$ .		· ·
(D)	momentum yiel $L_{i} = L_{f}$ $I_{i}\omega_{i} = I_{f}\omega_{f}$ $I_{A}\omega_{A} = (I_{A} + I_{A})$		
(E)		option uses conservation of rvation of angular moment	• •

Skill		Learning Objective	Topic
7.A		CON-6.B	Orbits of Planets and Satellites
(A)	the gravitationa	n setting the centripetal force I force between the satellite out of the equation; thus, the s orbit.	and Earth, the mass of the
(B)		e the satellite must be at a spific angular velocity.	pecific altitude, it must
(C)	Incorrect. While the satellite must have a specific angular velocity, the mass of the satellite is not a factor. When setting the centripetal force on the satellite equal to the gravitational force between the satellite and Earth, the mass of the satellite cancels out of the equation.		en setting the centripetal nal force between the
(D)	gravitational for into the equation equation, and the radius of orbit;	the centripetal force on the ree between the satellite and $F_C = F_g$ $\frac{mv^2}{r} = G\frac{Mm}{r^2}$ In yields $\frac{(r\omega)^2}{r} = G\frac{M}{r^2}$ $\omega^2 = G\frac{M}{r^3}$ The angular velocity of the satellite must be at a specific angular velocity, but a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity, but the satellite must be at a specific angular velocity.	tellite depends on the
(E)	Incorrect. While the satellite must be at a specific altitude and must have a specific angular velocity, the mass of the satellite is not a factor. When setting the centripetal force on the satellite equal to the gravitational force between the satellite and Earth, the mass of the satellite cancels out of the equation.		

Skill		Learning Objective	Topic
5.E		FLD-1.A	Gravitational Forces
(A)	Incorrect. This	option solves for the net force o	n sphere X but makes
	the distance of s	sphere Z as 2r.	
(B)	Incorrect. This	option is the force due to only s	phere Y , not the net
	force on sphere	X.	
(C)	<b>Correct</b> . Both sphere Y and Z will attract sphere X to the right. Adding the force of gravity from both spheres together and substituting into the equation for gravitational force yields		
	$F_g = F_{gy} + F_{gz}$	$=\frac{Gm_Xm_Y}{r_{XY}^2} + \frac{Gm_Xm_Z}{r_{XZ}^2} = \frac{Gm_X^2}{r_{XZ}^2}$	$\frac{c^2}{(3r)^2} + \frac{Gm(2m)}{(3r)^2} = \frac{11Gm^2}{9r^2}.$
(D)	Incorrect. This option adds the force of gravity from spheres Y and Z together but uses $2r$ instead of $3r$ for the distance for sphere Z and uses $m$ instead of $2m$ as the mass for Z.		
(E)		option adds the force of gravity es $r$ and $m$ for the distance and	-

Skill		Learning Objective	Topic
5.B		FLD-1.A	Gravitational Forces
(A)	for the two force	option uses the gravitationa es, but it uses the square roo the distance in the equation	ot of the distance instead
(B)	Incorrect. This option uses the gravitational force equation to solve for the two forces, but it does not square the distance in the equation. It also compares the radius of orbit for satellite A to the radius of the planet instead of the radius of orbit for satellite C.		
(C)	Incorrect. This option uses the gravitational force equation to solve for the two forces, but it does not square the distance in the equation.		
(D)	Incorrect. This option uses the gravitational force equation to solve for the two forces, but it does not square the distance in the equation. It also uses the radius of the planet instead of the radius of orbit for the distance for satellite A.		
(E)	the satellite in o Substituting into satellite in orbit	Λ	$\frac{A}{A} = \frac{Gm_Sm}{(3R)^2} = \frac{1}{9} \frac{Gm_Sm}{R^2}.$ Examinational force on the $\frac{Gm_Sm}{(12R)^2} = \frac{1}{144} \frac{Gm_Sm}{R^2}.$ $= \frac{Gm_Sm}{R^2}$
	Combing the tw	To equations yields $9F_{\rm A}=1$ $F_{\rm A}=16$	

Skill		Learning Objective	Topic
5.B		CON-6.A	Orbits of Planets and Satellites
(A)	Incorrect. This option solves for the ratio of the speeds of satellite C to satellite A instead of the ratio of the speeds of satellite A to satellite C.		
(B)	affect the speed	option indicates that the rac of the satellite. However, as eed of the satellite will decr	the radius of orbit
(C)	and solving for the Repeating for sa	speed of the satellite will decrease. Ing the centripetal force equal to the gravitational force $F_C = F_g$ or the speed of satellite A yields $\frac{m_A v_A^2}{r_A} = \frac{GMm_A}{r_A^2}.$ $v_A = \sqrt{\frac{GM}{r_A}}$ $F_C = F_g$ satellite C yields $\frac{m_C v_C^2}{r_C} = \frac{GMm_C}{r_C^2}.$ Taking the ratio $v_C = \sqrt{\frac{GM}{r_C}}$ eds yields $\frac{v_A}{v_C} = \frac{\sqrt{\frac{GM}{r_A}}}{\sqrt{\frac{GM}{r_C}}} = \sqrt{\frac{r_C}{r_A}} = \sqrt{\frac{12R}{3R}} = \frac{2}{1}.$	
(D)	Incorrect. This option solves for the ratio of the square of the speeds instead of the ratio of the speeds.		
(E)	inversely propor	Incorrect. This option indicates that the speed of the satellite is inversely proportional to the radius of orbit instead of the square root of the radius.	

Skill		Learning Objective	Topic
5.B		FLD-1.A	Gravitational Forces
(A)	Incorrect. This of tension on the n	option solves for the tension new planet.	n on Earth in terms of the
(B)	Incorrect. This option solves for the tension on the planet with the assumption that the mass of the new planet is the same with Earth's, but it has twice the radius. Thus, the weight of the object will be quarter of its value on Earth.		
(C)	Incorrect. This option indicates that the force does not depend on the planet. However, if the value of the acceleration is different on the new planet, the tension in the string will also be different.		
(D)	block; thus, it we gravity. Setting to on an object and $F_W = F_g$ $mg = G \frac{Mm}{R^2}$ $g = G \frac{\rho V}{R^2} = G$ new planet is the	nsion in the string will depend ill depend on the value of the the weight of an object equal substituting for density yields $\frac{\rho\left(\frac{4}{3}\pi R^3\right)}{R^2} = \frac{4}{3}G\rho\pi R$ is same and the radius is twice to gravity and the tension	ne acceleration due to all to the force of gravity elds us, if the density of the
(E)	Incorrect. This of for tension.	option does not square the o	distance in the equation

Skill		Learning Objective	Topic	
6.B		INT-5.B	Impulse and Momentum	
(A)		Incorrect. This solution uses impulse-momentum to solve for time and then divides by 6 in an incorrect attempt to convert to minutes.		
(B)		solution sets the impulse eq t it substitutes the force for equation.		
(C)	Incorrect. This solution sets the impulse equal to the change in momentum, but it substitutes the force for the mass and the mass for the force in the equation. It also includes a one-half term in the equation similar to the kinetic energy equation.			
(D)	Correct. Setting the impulse equal to the change in momentum of the shuttle and solving for time yields $J = \Delta p$ $Ft = m(v_f - v_i)$ $t = \frac{m(v_f - v_i)}{F} = \frac{(90000 \text{ kg})(8000 \text{ m/s} - 7900 \text{ m/s})}{(50000 \text{ N})} = 180 \text{ s}$			
(E)	Incorrect. This solution sets the impulse equal to the change in momentum, but it substitutes the force for the mass and the mass for the force in the equation. It also includes a one-fourth term in the equation similar to the squaring of the speed in the kinetic energy equation.			

Skill		Learning Objective	Topic
5.B		INT-8.K	Simple Harmonic Motion, Springs, and Pendulums
(A)	remain the same oscillation of a s	e the period of oscillation for e, according to the equation apring is proportional to the ess of the block increases, the ess not decrease.	for the period of square root of the mass.
(B)	$T_P = 2\pi \sqrt{\frac{L}{g}}$ , remain the same	ding to the equation for the mass is not a factor; thus, the e. According to the equation $\sqrt{\frac{m}{k}}$ , as the mass of the blo creases.	e period of oscillation will n for the period of a
(C)	Incorrect. The period of oscillation for the pendulum does not depend on mass, so it will remain the same. However, the period of oscillation of a spring is mass dependent, and it cannot not remain the same when the mass is doubled.		However, the period of
(D)	Incorrect. According to the equation for the period of oscillation of a pendulum, as the mass of the block increases, the period of oscillation remains the same. It does not increase. According to the equation for the period of oscillation of a spring, as the mass of the block increases, the period of oscillation increases, not decreases.		
(E)	according to the	e the period of oscillation for e equation for the period of cillation remains the same.	oscillation of a pendulum,

Skill		Learning Objective	Topic
5.B		INT-8.E	Simple Harmonic Motion, Springs, and Pendulums
(A)	the spring-block	rientation does not affect the system, the time to reach retem B as it was for system	naximum speed will be
(B)	the block that is the block, causing spring-block systaffect the period	pption indicates that the corparallel to the incline will a ng a decrease in the period otem. However, the orientate of oscillation; thus, the time cted by the orientation of the corporation of the corpo	of oscillation of the ion of the system does not the to reach maximum
(C)	the block that is moves up the in of the spring-blo does not affect t	option indicates that the conparallel to the incline will soline which will increase thock system. However, the other period of oscillation; thut is not affected by the orier	low down the block as it e period of one oscillation rientation of the system as, the time to reach
(D)	weight of the blo and it reduces th However, the or	option indicates that only the ock that is perpendicular to the period of oscillation of the ientation of the system does, the time to reach maximum of the system.	the incline is significant, ne spring-block system. s not affect the period of
(E)	the block that is of oscillation of the system does	pption indicates that the conperpendicular to the inclin the spring-block system. He not affect the period of oscion speed is not affected by the	e will increase the period owever, the orientation of illation; thus, the time to

Skill		Learning Objective	Topic	
5.E		INT-8.I	Simple Harmonic Motion, Springs, and Pendulums	
(A)	1. However, it a the kinetic energ square of the po	option indicates that the rat lso indicates that the poten gy. Because the potential en sition, it will have one-four ess than, not greater than, th	tial energy is greater than ergy is proportional to the th its maximum value;	
(B)	between its releated has twice the value potential energy	option indicates that because ase and equilibrium position lue of the kinetic energy. Ho is proportional to the squa its maximum value; thus, it e kinetic energy.	ns, the potential energy owever, because the are of the position, it will	
(C)	between its release and potential en would be equal to is proportional to	option indicates that because and equilibrium position tergy must be half their may to each other. However, because the square of the positions when the block is in this personal terms.	ns, both the kinetic energy kimum value, and they cause the potential energy n, it will not have half the	
(D)	Incorrect. This option indicates that because the block is halfway between its release and equilibrium positions, the potential energy is half its maximum value; thus, the kinetic energy has twice the value of the potential energy. However, because the potential energy is proportional to the square of the position, it will not have half the maximum value when the block is in this position.			
(E)	<b>Correct.</b> The total mechanical energy of the system is the sum of the elastic potential energy of the spring-block system and the kinetic energy of the block. When the block is at its maximum displacement the kinetic energy is zero and all the energy is elastic potential energy. Substituting into the equation for elastic potential energy yields $E = U_{Smax} = \frac{1}{2}kx_{max}^2 = \frac{1}{2}kd^2$ . Substituting into the			
	equation for the halfway from its	elastic potential energy equ maximum displacement yi	uation when the block is ields	
	$U_S = \frac{1}{2}k(\frac{1}{2}d)^2$	$d^2 == \frac{1}{8}kd^2$ . Substituting in	to conservation of energy	
	$E = U_S + K$ $\frac{1}{2}kd^2 = \frac{1}{8}kd^2$ $K = \frac{3}{8}kd^2$	kinetic energy of the block $Y$ + $K$ ; thus, the ratio of the $Y$	kinetic energy to the	
	elastic potential	energy is $\frac{K}{U} = \frac{\frac{3}{8}kd^2}{\frac{1}{8}kd^2} = \frac{3}{1}$ .		

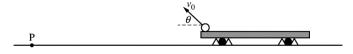
Skill		Learning Objective	Topic	
2.C		CON-1.D	Forces and Potential Energy	
(A)		tution into a Newton's second law equation for the $F_{net} = 0 = F_S - W \sin \theta$ rium in system B yields $k(\Delta x) = mg \sin \theta$ ;		
		to the spring constant, the incline, the stretch $\Delta x$ of the		
(B)	Incorrect. Newton's second law equation for the block at equilibrium in system B yields $g = \frac{k(\Delta x)}{m \sin \theta}$ ; thus, the speed of the block is not			
(C)	· · · · · · · · · · · · · · · · · · ·	ermine a value for g.		
(C)	Incorrect. Newton's second law equation for the block at equilibrium in system B yields $g = \frac{k(\Delta x)}{m\sin\theta}$ ; thus, the stretch $\Delta x$ of the spring			
	must be known, but the speed of the block is not necessary to			
	determine a value for g.			
(D)	Incorrect. Newton's second law equation for the block at equilibrium in system B yields $g = \frac{k(\Delta x)}{m\sin\theta}$ ; thus, neither the speed of the block			
	nor the time interval between two consecutive passes through the equilibrium position is necessary to determine a value for $g$ .			
(E)		on's second law equation fo	_	
		$\operatorname{lds} g = \frac{k(\Delta x)}{m \sin \theta}; \text{ thus, the s}$		
		but the time interval between ilibrium position is not nec		

Skill		Learning Objective	Topic
6.B		CON-1.D	Forces and Potential Energy
(A)	amplitude of ose equation for the	option uses Newton's secon cillation but includes the on e elastic potential energy. It to gravity in the calculation	ne-half term similar to the also does not include the
(B)		option uses Newton's secon cillation but does not includ lculation.	
(C)	Incorrect. This option uses Newton's second law to determine the amplitude of oscillation but then divides the answer by two, because the block moves the same distance on both sides of the equilibrium position. However, the solution from the equation is the amplitude of oscillation.		
(D)	of oscillation, N the block will no Substituting into $F_{net} = 0 = F_S - kx_{max} = mg$	ring begins unstretched. To ewton's second law can be sow stretch the spring to the so Newton's second law yield $F_W = \frac{(2.0 \text{ kg})(9.8 \text{ m/s}^2)}{(100 \text{ N/m})} = 0.20 \text{ m}$	used to determine how far equilibrium position. ds
(E)	amplitude of ose block moves thi	option uses Newton's secon cillation but then doubles the s distance on both sides of the clution from the equation is	ne answer, because the the equilibrium position.

### **Question 1**

15 points total

Distribution of points



Note: Figure not drawn to scale.

A projectile is launched from the back of a cart of mass m that is held at rest, as shown above. At time t = 0, the projectile leaves the cart with speed  $v_0$  at an angle  $\theta$  above the horizontal. The projectile lands at point P. Assume that the starting height of the projectile above the ground is negligible compared to the maximum height reached by the projectile and the horizontal distance traveled.

(a) LO CHA-2.C, SP 5.A, 5.E 2 points

Derive an expression for the time  $t_P$  at which the projectile reaches point P. Express your answer in terms of  $v_0$ ,  $\theta$ , and physical constants, as appropriate.

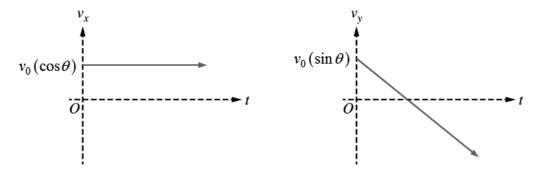
For using an appropriate kinematics equation to calculate the time to the highest point of the flight		1 point
$v_x = v_{x0} + a_x t : v_y = v_{y0} + a_y t_{top}$		
For substituting into the equation above and doubling the time		1 point
$0 = v_0(\sin\theta) - gt_{\text{top}} :: t_{\text{top}} = \frac{v_0(\sin\theta)}{g}$		
$t = 2t_{\text{top}} = \frac{2v_0(\sin\theta)}{g}$		
Alternate solution Al	lterr	ate Points
For using an appropriate kinematics equation to calculate the time of flight		1 point
$x = x_0 + v_{x0}t + \frac{1}{2}a_xt^2 : \Delta y = v_{1y}t + \frac{1}{2}a_yt^2$		
For substituting into the equation above		1 point
$0 = v_0(\sin\theta)t - \frac{1}{2}gt^2 \therefore t = \frac{2v_0(\sin\theta)}{g}$		

### **Question 1 (continued)**

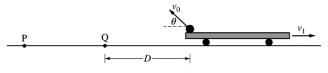
Distribution of points

(b) LO CHA-2.C, SP 3.C, 4.D 5 points

On the axes below, sketch the horizontal component  $v_x$  and the vertical component  $v_y$  of the velocity of the projectile as a function of time t from t = 0 until  $t = t_P$ . Explicitly label the vertical intercepts with algebraic expressions.



For a straight horizontal line with positive values on the $v_x$ graph	1 point
For correctly indicating the y-intercept on the $v_x$ graph	1 point
For a straight line with an initially positive value on the $v_y$ graph	1 point
For a line with negative slope that crosses the horizontal axis on the $v_y$ graph	1 point
For correctly indicating the y-intercept on the $v_y$ graph	1 point



Note: Figure not drawn to scale.

The projectile is again launched from the same position, but with the cart traveling to the right with speed  $v_1$  relative to the ground, as shown above. The projectile again leaves the cart with speed  $v_0$  relative to the cart at an angle  $\theta$  above the horizontal, and the projectile lands at point Q, which is a horizontal distance D from the launching point. Express your answers in terms of  $v_0$ ,  $\theta$ , and physical constants, as appropriate.

### **Question 1 (continued)**

Distribution of points

(c) LO CHA-2.A.f, SP 7.D 1 point

Give a physical reason why the projectile lands at point Q, which is not as far from the launch position as point P is, and explain how that physical reason affects the flight of the projectile.

For an appropriate physical reason and correct explanation	1 point
Claim: The projectile will not travel as far as the stationary case.	
Evidence: The rightward component of velocity causes the initial horizontal launch	
velocity of the projectile with respect to the ground to be less than when the cart was	
stationary.	
Reasoning: The projectile had a component of velocity to the right with respect to the	
ground at the time of launch.	

(d) LO CHA-2.A.f, SP 5.A, 5.E 2 points

Derive an expression for  $v_1$ . Express your answer in terms of  $v_0$ ,  $\theta$ , D, and physical constants, as appropriate.

For a correct expression for the horizontal component of the velocity of the projectile	1 point
$v_x = v_0(\cos\theta) - v_1$	
For correctly substituting into the equation for constant speed	1 point
$\Delta x = v_x t : D = (v_0(\cos\theta) - v_1)(2v_0(\sin\theta)/g)$	
$\frac{D}{2v_0(\sin\theta)/g} = v_0(\cos\theta) - v_1 :: v_1 = v_0(\cos\theta) - \frac{gD}{2v_0(\sin\theta)}$	-

After the launch, the cart's speed is  $v_2$ . Beginning at time t = 0, the cart experiences a braking force of F = -bv, where b is a positive constant with units of kg/s and v is the speed of the cart. Express your answers to the following in terms of m, b,  $v_2$ , and physical constants, as appropriate.

### **Question 1 (continued)**

Distribution of points

(e)

i) LO INT-1.H.a, SP 5.A 1 point

Using Newton's second law, write but DO NOT solve a differential equation that represents the motion of the cart while it experiences the braking force.

For an appropriate differential equation	1 point
F = ma	
$-bv = m\frac{dv}{dt}$	

ii) LO INT-1.H.b, SP 5.E 2 points

Show that the speed v(t) of the cart as a function of time is given by the equation  $v(t) = v_2 e^{-bt/m}$ .

For a correct separation of variable in the above differential equation	1 point
$-\frac{b}{m}dt = \frac{1}{v}dv$	
For integrating with appropriate limits or constant of integration	1 point
$-\int_{t'=0}^{t'=t} \frac{b}{m} dt' = \int_{v=v_2}^{v=v(t)} \frac{1}{v} dv : -\left[\frac{b}{m}t'\right]_{t'=0}^{t'=t} = \left[\ln(v)\right]_{v=v_2}^{v=v(t)}$	
$-\frac{b}{m}(t-0) = \ln(v(t)) - \ln(v_2) = \ln\left(\frac{v(t)}{v_2}\right)$	
$e^{-bt/m} = \frac{v(t)}{v_2} :: v(t) = v_2 e^{-bt/m}$	

iii) LO CHA-1.B, SP 5.E 2 points

Derive an expression for the distance the cart travels from t = 0 until the time it comes to a stop.

For indicating that the distance traveled is the integration of the above equation	1 point
$\Delta x = \int v dt = \int v_2 e^{-bt/m} dt$	
For integrating with appropriate limits or constant of integration	1 point
$\Delta x = \int_{t=0}^{t=\infty} v_2 e^{-bt/m} dt = v_2 \left( -\frac{m}{b} \right) \left[ e^{-bt/m} \right]_{t=0}^{t=\infty} = -\frac{mv_2}{b} \left( \frac{1}{e^{\infty}} - \frac{1}{e^0} \right)$	
$\Delta x = -\frac{mv_2}{b}(0-1) = \frac{mv_2}{b}$	

#### **Question 1 (continued)**

#### **Learning Objectives**

- **CHA-1.B** Determine functions of position, velocity, and acceleration that are consistent with each other, for the motion of an object with a nonuniform acceleration.
- **CHA-2.A.f** Describe the velocity vector for one object relative to a second object with respect to its frame of reference.
- **CHA-2.C** Calculate kinematic quantities of an object in projectile motion, such as: displacement, velocity, speed, acceleration, and time, given initial conditions of various launch angles, including a horizontal launch at some point in its trajectory.
- **INT-1.H.a** Derive an expression for the motion of an object freely falling with a resistive drag force (or moving horizontally subject to a resistive horizontal force).
- **INT-1.H.b** Describe the acceleration, velocity, or position in relation to time for an object subject to a resistive force (with different initial conditions, i.e., falling from rest or projected vertically).

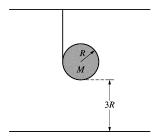
#### **Science Practices**

- **3.C** Sketch a graph that shows a functional relationship between two quantities.
- **4.D** Select relevant features of a graph to describe a physical situation or solve problems.
- **5.A** Select an appropriate law, definition, or mathematical relationship or model to describe a physical situation.
- **5.E** Derive a symbolic expression from known quantities by selecting and following a logical algebraic pathway.
- **7.D** Provide reasoning to justify a claim using physical principles or laws.

#### **Question 2**

15 points total

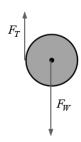
Distribution of points



A thin uniform disk of mass M and radius R has a string wrapped around its edge and attached to the ceiling. The bottom of the disk is at a height 3R above the floor, as shown above. The disk is released from rest. The rotational inertia of a disk around its center is  $I = MR^2/2$ .

(a) LO INT-6.B.a, SP 3.D 2 points

On the circle below that represents the disk, draw and label the forces (not components) that act on the disk. Each force must be represented by a distinct arrow starting on, and pointing away from, the disk, beginning at the point where the force is exerted on the disk. The dot is at the center of the disk.



For drawing and labeling the weight of the block directed downward starting at the	1 point
center of the disk	
For drawing and labeling the tension directed upward starting at the left edge of the disk	1 point
Note: A maximum of one point can be earned if there are any extraneous vectors.	

(b) LO INT-7.B.a, SP 7.A, 7.C 2 points

When released from rest, the disk falls and the string unwinds. The force the string exerts on the disk is  $F_T$ , and the gravitational force exerted on the disk is  $F_g$ . Which of the following expressions correctly relates  $F_T$  and  $F_g$  as the disk falls?

$$\underline{\qquad} F_T < F_g \qquad \underline{\qquad} F_T = F_g \qquad \underline{\qquad} F_T > F_g$$
 Justify your answer.

For selecting " $F_T < F_g$ "	1 point
For a correct justification	1 point
Example Justification: The center of mass of the disk accelerates downward, so the	
force of gravity must be greater than the tension in the string.	

### **Question 2 (continued)**

Distribution of points

(c)

Express all answers in terms of M, R, and physical constants, as appropriate.

i) LO INT-7.C, SP 5.A, 5.E 4 points

Derive an expression for the acceleration a of the disk as it falls.

E ' CN , 2 11 ' 1' C	1 1
For an expression of Newton's second law in linear form	1 point
$F_{net} = ma : Mg - F_T = Ma$	
For an expression of Newton's second law in rotational form	1 point
$\tau = I\alpha : F_T R = \frac{1}{2} M R^2 \alpha$	
For correctly relating the linear and rotational accelerations	1 point
$F_T R = \frac{1}{2} M R^2 \left(\frac{a}{R}\right) :: F_T = \frac{1}{2} M a$	
For combining the two equations	1 point
$Mg - \frac{1}{2}Ma = Ma : a = \frac{2}{3}g$	
Alternate Solution	Alternate Points
For a clear indication of using the point of contact between the string and the disk as the axis of rotation	1 point
For deriving an expression for the rotational inertia of the disk around an edge	1 point
$I = I + Mh^2 = \frac{1}{2}MR^2 + MR^2 = \frac{3}{2}MR^2$	
For an expression of Newton's second law in rotational form	1 point
$\tau = I\alpha : MgR = \frac{3}{2}MR^2\alpha$	
For correctly relating the linear and rotational accelerations	1 point
$MgR = \frac{3}{2}MR^2\left(\frac{a}{R}\right) :: a = \frac{2}{3}g$	

### **Question 2 (continued)**

Distribution of points

(c) con't

Derive an expression for the time  $\Delta t$  that it takes the disk to reach the ground.

For correctly substituting the distance into a kinematic equation to calculate the time		1 point
$\Delta y = v_1 t + \frac{1}{2} a t^2 :: 3R = 0 + \frac{1}{2} a t^2$		
For substituting the acceleration from part (c)(i) into equation above		1 point
$3R = \frac{1}{3}gT^2 :: T = 3\sqrt{\frac{R}{g}}$		

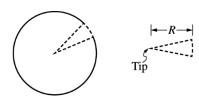
iii) LO INT-7.D.b, SP 5.E 1 point

Derive an expression for the rotational kinetic energy  $K_{\text{rot}}$  of the disk at the instant it reaches the ground.

For correctly substituting into an equation for the rotational kinetic energy of the disk		1 point
$K = \frac{1}{2}I\omega^2 = \frac{1}{2}\left(\frac{1}{2}MR^2\right)(\alpha t)^2 = \left(\frac{1}{4}MR^2\right)\left(\frac{a}{R}\right)^2\left(3\sqrt{\frac{R}{g}}\right)^2$		
$K = \left(\frac{1}{4}M\right)\left(\frac{2}{3}g\right)^2\left(\frac{9R}{g}\right) = MgR$		
11		
Alternate solution	Alteri	nate points
Alternate solution  For correctly substituting into an equation for the rotational kinetic energy of the disk	Alteri	nate points 1 point
	Alteri	

### **Question 2 (continued)**

Distribution of points



Note: Figure not drawn to scale.

(d)

A very narrow wedge is cut out of the thin uniform disk of mass M, as shown above. If r is the distance from the tip of the wedge, then the linear mass density of the wedge can be expressed as follows:

$$\lambda(r) = \frac{Mr}{25R^2}.$$

i. LO INT-6.D.c, SP 5.A, 5.E 3 points

Using integral calculus, derive an expression for the rotational inertia of the wedge around its tip.

For integrating an appropriate equation to calculate rotational inertia of the wedge	1 point
$I = \int r^2 dm$	
$m = \lambda r :. dm = \lambda dr = \frac{Mr}{25R^2} dr$	
For correctly substituting into equation for rotational inertia	1 point
$I = \int r^2 \left(\frac{Mr}{25R^2}\right) dr = \frac{M}{25R^2} \int r^3 dr$	
For integrating with appropriate limits or constant of integration	1 point
$I = \frac{M}{25R^2} \int_{r=0}^{r=R} r^3 dr = \frac{M}{25R^2} \left[ \frac{r^4}{4} \right]_{r=0}^{r=R} = \frac{M}{25R^2} \left( \frac{R^4}{4} - 0 \right) = \frac{1}{100} MR^2$	

ii. LO INT-6.D.c, SP 5.E 1 point

Derive an expression for the rotational inertia of the modified disk (i.e., the disk after the narrow wedge is cut out) around its original center.

For correctly using superposition to determine the rotational inertia of the disk without the wedge		1 point
1 2 1 2 40 2		
$I_{tot} = I_{disk} - I_{wedge} = \frac{1}{2}MR^2 - \frac{1}{100}MR^2 = \frac{49}{100}MR^2$		

#### **Question 2 (continued)**

#### **Learning Objectives**

**CHA-1.A.b** – Calculate unknown variables of motion such as acceleration, velocity, or positions for an object undergoing uniformly accelerated motion in one dimension.

**INT-6.B.a** – Describe the two conditions of equilibrium for an extended rigid body.

**INT-6.D.c** – Derive the moments of inertia for a thin cylindrical shell or disc about its axis or an object that can be considered to be made up of coaxial shells (e.g., annular ring).

**INT-7.B.a** – Describe the net torque experienced by a rigid extended body in situations such as, but not limited to, rolling down inclines, pulled along horizontal surfaces by external forces, a pulley system (with rotational inertia), simple pendulums, physical pendulums, and rotating bars.

**INT-7.**C – Derive expressions for physical systems such as Atwood Machines, pulleys with rotational inertia, or strings connecting discs or strings connecting multiple pulleys that relate linear or translational motion characteristics to the angular motion characteristics of rigid bodies in the system that are: **(a)** rolling (or rotating on a fixed axis) without slipping. **(b)** rotating and sliding simultaneously.

**INT-7.D.b** – Calculate the total kinetic energy of a rolling body or a body that has both translation and rotational motion.

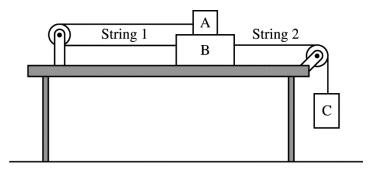
#### **Science Practices**

- **3.D** Create appropriate diagrams to represent physical situations.
- **5.A** Select an appropriate law, definition, or mathematical relationship or model to describe a physical situation.
- **5.E** Derive a symbolic expression from known quantities by selecting and following a logical algebraic pathway.
- 7.A Make a scientific claim.
- 7.C Support a claim with evidence from physical representations.

#### **Question 3**

15 points total

Distribution of points

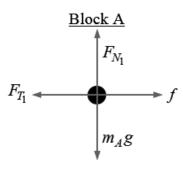


Three blocks are connected by strings that pass over pulleys of negligible mass. Block B is on a level, horizontal surface of negligible friction. Block A is on top of block B. String 1 connects blocks A and B. The coefficients of static and kinetic friction between blocks A and B are  $\mu_s$  and  $\mu_k$ , respectively. Block C is hanging over the end of the table and is attached to block B by string 2, as shown above. The masses of blocks A, B, and C are  $m_A$ ,  $m_B$ , and  $m_C$ , respectively. When block C is released, the system remains at rest.

(a)

i) LO INT-1.A, SP 3.D 2 points

On the dot below, which represents block A, draw and label the forces (not components) that act on block A. Each force must be represented by a distinct arrow starting on, and pointing away from, the dot.



For correctly drawing and labeling the vertical forces on block A	1 point
For correctly drawing and labeling the horizontal forces on block A	1 point
Note: A maximum of one point can be earned if there are any extraneous vectors	

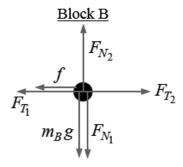
### **Question 3 (continued)**

Distribution of points

(a) con't

ii) LO INT-1.A, SP 3.D 3 points

On the dot below, which represents block B, draw and label the forces (not components) that act on block B. Each force must be represented by a distinct arrow starting on, and pointing away from, the dot.



For correctly drawing and labeling the vertical forces on block B	1 point
For correctly drawing and labeling the tension in string 1 to the left and the tension in	1 point
string 2 to the right on block B	
For correctly drawing and labeling the static friction to the left on block B	1 point
Note: A maximum of two points can be earned if there are any extraneous vectors	

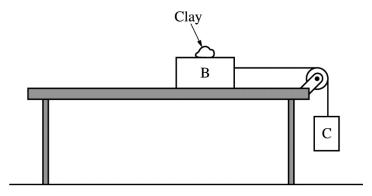
(b) LO INT-1.B.b, SP 5.A, 5.E 3 points

Derive an expression for the maximum value for  $m_C$  at which the blocks will remain at rest. Express all algebraic answers in terms of  $\mu_s$ ,  $\mu_k$ ,  $m_A$ ,  $m_B$ ,  $m_C$ , and physical constants, as appropriate.

For an expression of Newton's second law on block B	1 point
$F_{T_2} - f - F_{T_1} = m_B a = 0 : F_{T_2} = f + F_{T_1}$	
Expression of Newton's second law on blocks A and C	
$F_{T_1} - f = m_{\mathcal{A}}a = 0 : F_{T_1} = f$	
$m_C g - F_{T_2} = m_C a = 0 : F_{T_2} = m_C g$	
For a correct expression for the frictional force	1 point
$f = \mu_{\rm S} F_{\rm N} = \mu_{\rm S} m_{\rm A} g$	
$F_{T_2} = m_{\rm C}g = f + f = 2f = 2\mu_{\rm S}m_{\rm A}g$	
For an answer consistent with part (a)(ii)	1 point
$m_{\rm C} = 2\mu_{\rm s}m_{\rm A}$	

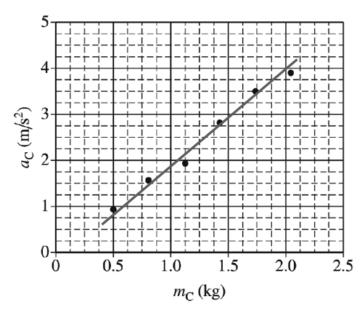
### **Question 3 (continued)**

Distribution of points



The setup is modified, as shown in the figure above. Block A and one of the pulleys are removed, and block B remains on the table. There is still negligible friction between block B and the table. A lump of clay is added to block B. The students use Newton's second law to derive an equation for the acceleration  $a_{\rm C}$  of block C. The acceleration is given by the equation  $a_{\rm C} = m_{\rm C} g/m_{\rm tot}$ , where  $m_{\rm tot}$  is the combined mass of the clay and the two blocks. Students use the setup shown above to experimentally determine the acceleration g due to gravity. In each trial, a student moves a small amount of clay from block B to block C and then releases the blocks from rest, recording the new values of  $m_{\rm C}$  and  $a_{\rm C}$ . The total mass of the clay and the two blocks is  $m_{\rm tot} = 5.0~{\rm kg}$ . The graph below shows  $a_{\rm C}$  as a function of  $m_{\rm C}$ , where  $m_{\rm C}$  is now the combined mass of block C and the mass of clay added to block C.

Draw a best-fit line to the data points in the graph above.



For drawing an appropriate best-fit line	oint
--	------

### **Question 3 (continued)**

Distribution of points

(c) con't

ii) LO INT-1.C.e, SP 4.D, 6.C 3 points

Use the best-fit line from part (c)(i) to calculate an experimental value for the acceleration g due to gravity.

For calculating the slope from the best-fit line and not from the data points unless the data points fall on the best-fit line	1 point
slope = $\frac{\Delta y}{\Delta x} = \frac{(4.0 - 1.0)(\text{m/s}^2)}{(2.05 - 0.52)(\text{kg})} = 2.0 \text{m/kg} \cdot \text{s}^2$	
For correctly relating the slope to <i>g</i>	1 point
$slope = \frac{g}{m_{tot}} :: g = m_{tot} \times slope$	
For calculating an experimental value for g with units	1 point
$g = m_{tot} \times \text{slope} = (5.0 \text{ kg})(2.0 \text{ m/kg} \cdot \text{s}^2) = 10.0 \text{ m/s}^2$	

(d) LO INT-7.A.a, SP 7.A, 7.C 1 point

If the mass of the pulley in part (c) is significant, would the experimental value of g be greater than, less than, or equal to the value calculated in part (c)(ii)?

Greater than	Less than	Equal to
Justify your answer.		

Select "Less than"	
For a correct justification	1 point
Example Justification: If the pulley has mass, the system will have more inertia and	
therefore the acceleration of the system be less. If the acceleration of the system is	
less, the experimental value of g is less.	
Note: "Greater than" is accepted if the student provides a reasonable justification.	

A different group of students repeats the experiment, but instead of moving clay from block B to block C, they just remove a small amount of clay from block B and set it aside, away from the setup. The equation  $a_{\rm C} = m_{\rm C} g/m_{\rm tot}$  still applies to the new experiment.

### **Question 3 (continued)**

Distribution of points

(e) LO INT-1.C.e, SP 7.A, 7.C 2 points

In order to provide a straight-line graph that can be used to determine an experimental value for g, what two quantities should the students now graph? Check all that apply.

$$a_c \text{ vs } \frac{1}{m_{tot}}$$
  $a_c \text{ vs } m_{tot}$   $a_c \text{ vs } \frac{m_c}{m_{tot}}$ 
 $a_c \text{ vs } m_C$   $m_c \text{ vs } m_{tot}$   $m_c \text{ vs } \frac{1}{m_{tot}}$ 

Justify your answer.

For selecting " $a_C$ vs $\frac{1}{m_{tot}}$ " and " $a_c$ vs $\frac{m_c}{m_{tot}}$ "	1 point
For a correct justification	1 point
Example Justification: By removing the clay, the total mass is a variable. As the total	
mass of the system is decreased, the acceleration increase; thus $a_C$ vs $\frac{1}{m_{tot}}$ and	
$a_c$ vs $\frac{m_c}{m_{tot}}$ will generate a straight line graph that can be used to determine an	
experimental value for g.	

#### **Question 3 (continued)**

Distribution of points

#### **Learning Objectives**

**INT-1.A** – Describe an object (either in a state of equilibrium or acceleration) in different types of physical situations such as inclines, falling through air resistance, Atwood machines, or circular tracks).

**INT-1.B.b** – Calculate a force of unknown magnitude acting on an object in equilibrium.

**INT-1.C.e** – Derive a complete Newton's second law statement (in the appropriate direction) for an object in various physical dynamic situations (e.g., mass on incline, mass in elevator, strings/pulleys, or Atwood machines).

**INT-7.A.a** – Describe the complete analogy between fixed axis rotation and linear translation for an object subject to a net torque.

#### **Science Practices**

- **3.D** Create appropriate diagrams to represent physical situations.
- **4.**C Linearize data and/or determine a best fit line or curve.
- **4.D** Select relevant features of a graph to describe a physical situation or solve problems.
- **5.A** Select an appropriate law, definition, or mathematical relationship or model to describe a physical situation.
- **5.E** Derive a symbolic expression from known quantities by selecting and following a logical algebraic pathway.
- **6.C** Calculate an unknown quantity with units from known quantities, by selecting and following a logical computational pathway.
- **7.A** Make a scientific claim.
- **7.C** Support a claim with evidence from physical representations.

## 2019 AP Physics C: Mechanics Scoring Worksheet

#### **Section I: Multiple Choice**

$$\begin{array}{ccc} \underline{\hspace{1cm}} & \times & 1.2857 &= & \\ \hline \text{Number Correct} & & & \text{Weighted Section I Score} \\ & \text{(out of 35)} & & \text{(Do not round)} \end{array}$$

#### **Section II: Free Response**

Question 1 
$$\frac{}{}$$
 (out of 15)  $\times$  1.0000 =  $\frac{}{}$  (Do not round)

Question 2  $\frac{}{}$  (out of 15)  $\times$  1.0000 =  $\frac{}{}$  (Do not round)

Question 3  $\frac{}{}$  (out of 15)  $\times$  1.0000 =  $\frac{}{}$  (Do not round)

Sum =  $\frac{}{}$  Weighted Section II Score (Do not round)

#### **Composite Score**

	+	=
Weighted	Weighted	Composite Score
Section I Score	Section II Score	(Round to nearest
		whole number)

AP Score Conversion Chart Physics C: Mechanics

,				
Composite				
Score Range	AP Score			
48-90	5			
36-47	4			
27-35	3			
21-26	2			
0-20	1			

## 2019 AP Physics C: Mechanics Question Descriptors and Performance Data

## **Multiple-Choice Questions**

Question	Skill	Learning Objective	Торіс	Key	% Correct
1	4.D	CHA-1.C	Kinematics - Motion in One Dimension	D	74
2	6.C	CHA-1.B	Kinematics - Motion in One Dimension	С	92
3	7.A	CHA-2.C	Kinematics - Motion in Two Dimensions	D	30
4	1.D	INT-2.C	Circular Motion	А	89
5	1.D	INT-2.C	Circular Motion	D	35
6	6.B	INT-2.A	Circular Motion	D	34
7	4.D	CHA-1.C	Kinematics - Motion in One Dimension	В	83
8	4.D	CHA-1.C	Kinematics - Motion in One Dimension	В	52
9	7.C	INT-1.E	Newton's Laws of Motion - First and Second Laws	E	48
10	7.A	INT-1.H	Newton's Laws of Motion - First and Second Laws	В	65
11	6.C	INT-1.C	Newton's Laws of Motion - First and Second Laws	В	71
12	6.C	INT-4.C	Work-Energy Theorem	В	34
13	6.C	CON-4.F	Conservation of Linear Momentum, Collisions	А	60
14	6.B	INT-4.C	Work-Energy Theorem	А	39
15	5.E	CON-2.C	Conservation of Energy	С	67
16	5.E	CON-2.C	Conservation of Energy	А	18
17	5.A	INT-8.D	Simple Harmonic Motion, Springs, and Pendulums	С	38
18	5.E	CON-4.A	Conservation of Linear Momentum, Collisions	С	88
19	5.E	CON-2.C	Conservation of Energy	А	77
20	6.A	INT-5.B	Impulse and Momentum	С	72
21	7.A	CON-4.E	Conservation of Linear Momentum, Collisions	E	43
22	5.E	INT-5.B	Impulse and Momentum	Е	25
23	7.A	INT-7.E	Rotational Dynamics and Energy	D	82
24	5.A	CON-5.D	Angular Momentum and Its Conservation	D	37
25	7.A	CON-6.B	Orbits of Planets and Satellites	D	47
26	5.E	FLD-1.A	Gravitational Forces	С	61
27	5.B	FLD-1.A	Gravitational Forces	E	69
28	5.B	CON-6.A	Orbits of Planets and Satellites	С	25
29	5.B	FLD-1.A	Gravitational Forces	D	15
30	6.B	INT-5.B	Impulse and Momentum	D	55
31	5.B	INT-8.K	Simple Harmonic Motion, Springs, and Pendulums	В	68
32	5.B	INT-8.E	Simple Harmonic Motion, Springs, and Pendulums	А	13
33	5.E	INT-8.I	Simple Harmonic Motion, Springs, and Pendulums	Е	14
34	2.C	CON-1.D	Forces and Potential Energy	А	22
35	6.B	CON-1.D	Forces and Potential Energy	D	38

## 2019 AP Physics C: Mechanics Question Descriptors and Performance Data

## **Free-Response Questions**

Question	Skill	Learning Objective	Topic	Mean Score
1	3.C 4.D 5.A 5.E 7.D	CHA-2.C CHA-2.A.f INT-1.H.a INT-1.H.b CHA-1.B	3.4	7.34
2	3.D 5.A 5.E 7.A 7.C	INT-7.C CHA-1.A INT-7.D INT-6.D INT-6.B.a INT-7.B.a	1.3 1.4 1.5	6.4
3	3.D 4.C 4.D 5.A 5.E 6.C 7.A 7.C 7.D	INT-1.A INT-1.B INT-1.C	5.2	7.35